

Compiling *MATLAB*

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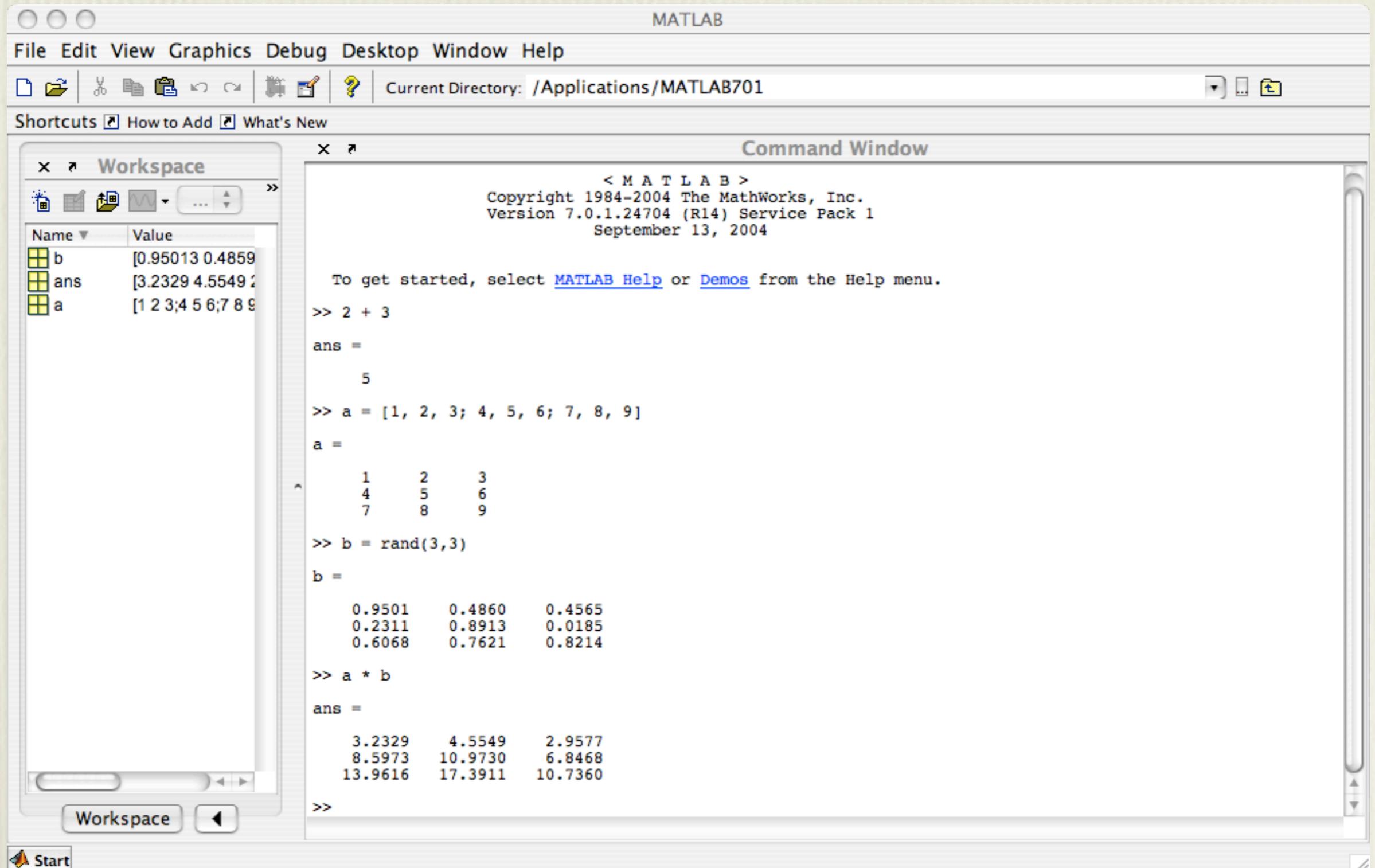
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Overview

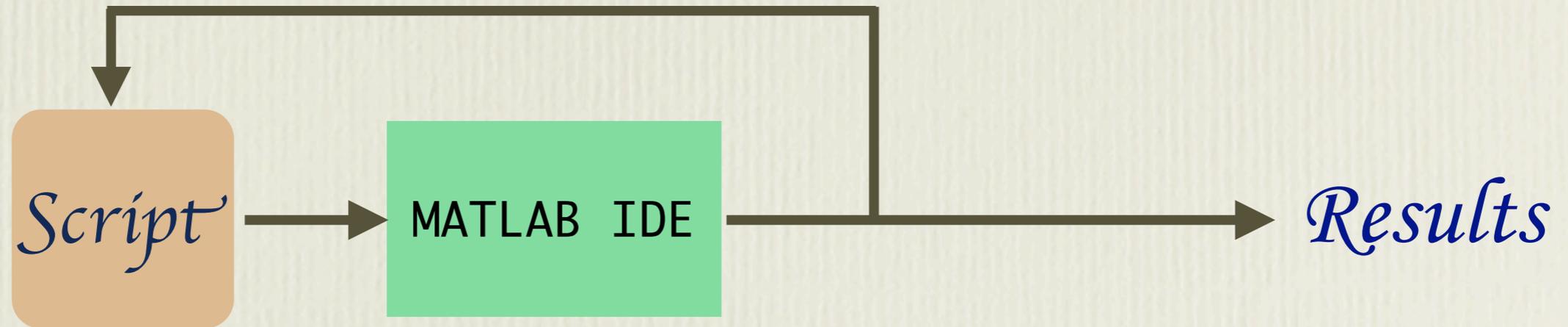
MATLAB IDE



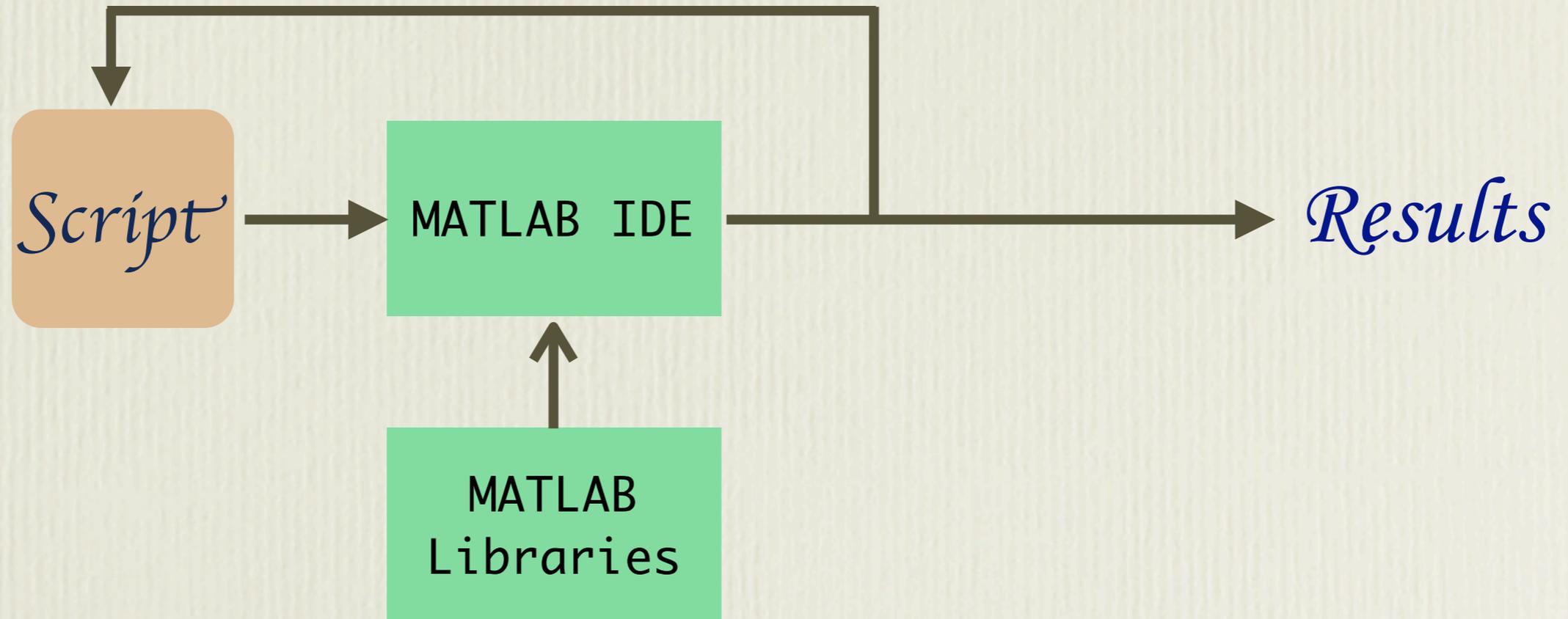
Why MATLAB?

- Ease of Use
 - writing
 - debugging
 - maintaining

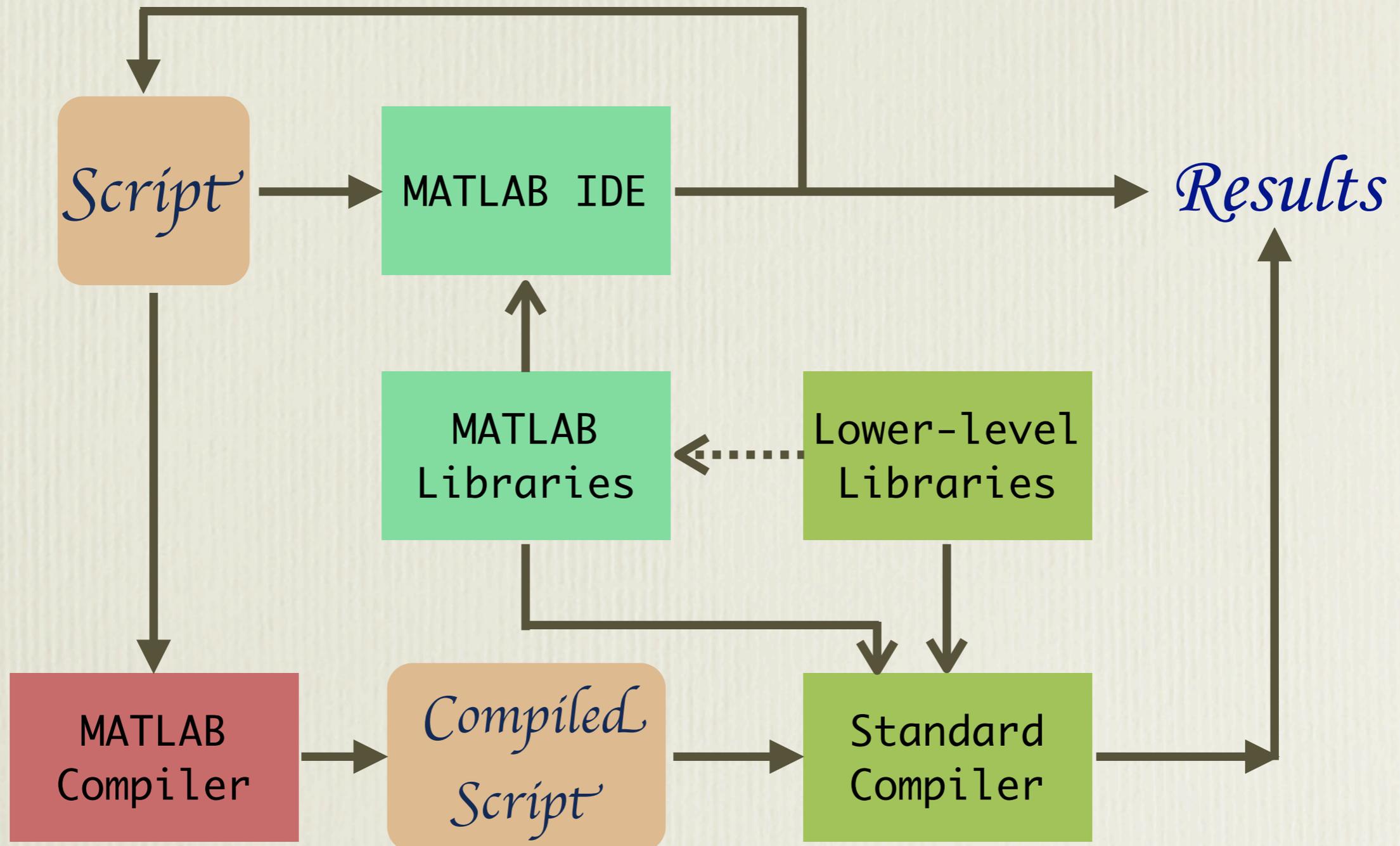
Operating Model



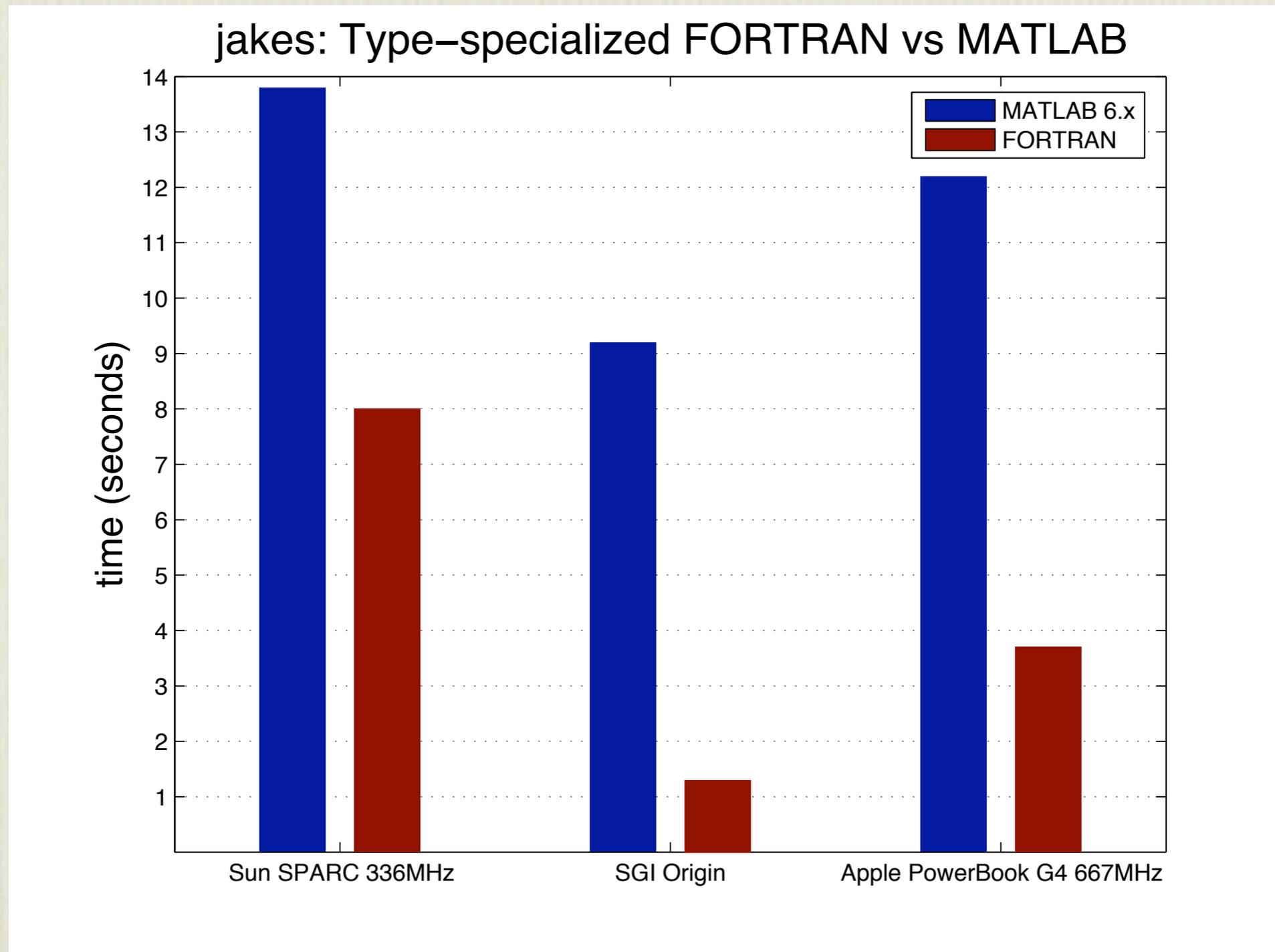
Operating Model



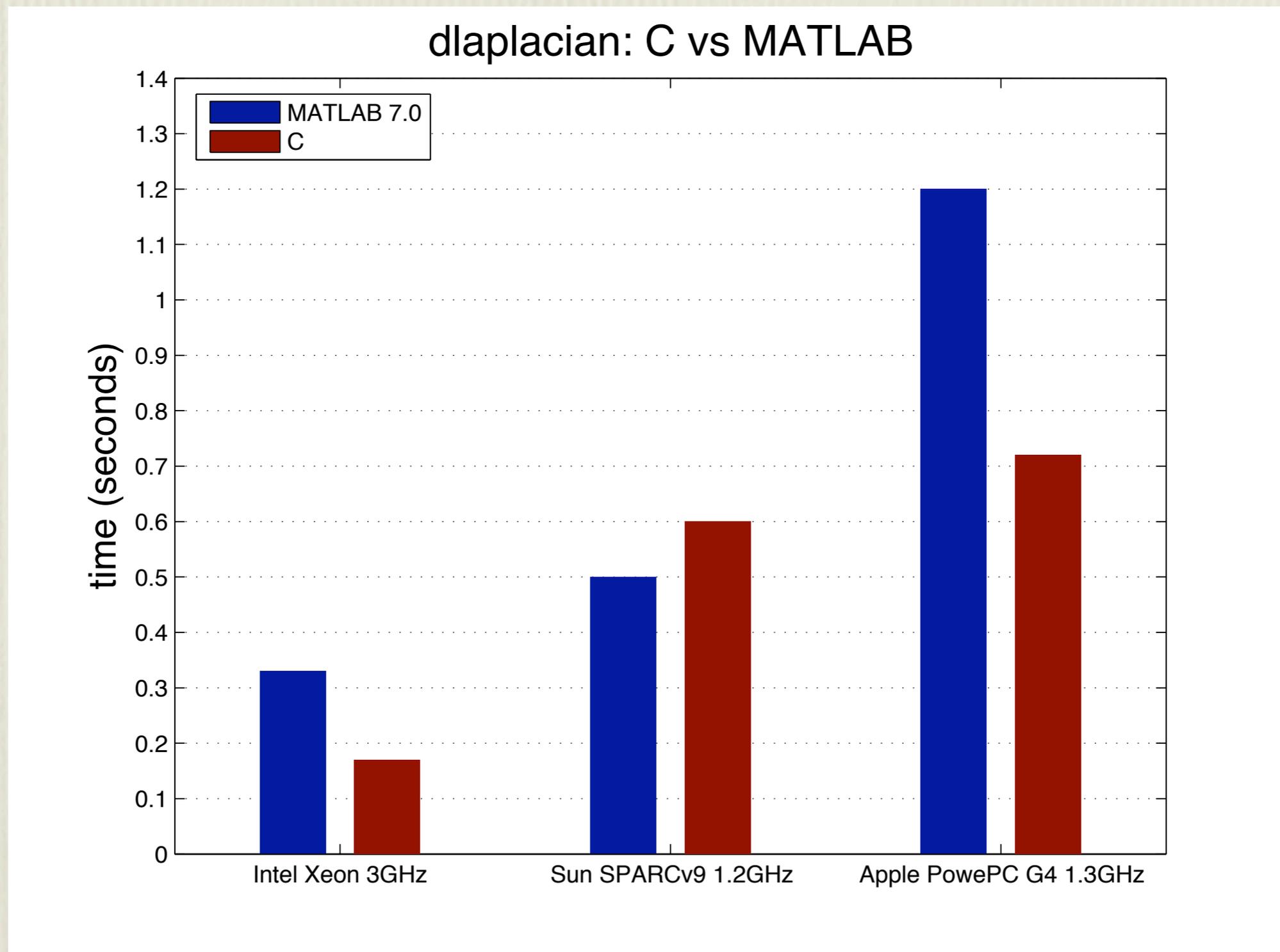
Operating Model



Lowering for Performance



Lowering for Performance (II)



Compiling and Lowering

- Lowering as the first step
 - enabled by type inference
- High-level operators enable contextual analysis
 - standard black-box technique is inadequate
- Compiler awareness of additional properties
 - annotations by library developers
 - automatic discovery

Optimizing Libraries

```
for ii = 1:200
  ...
  chan = jakes_mp1 (16500, 160, ii, num_paths);
  ...
  for snr = 2:2:20
    ...
    [s,x,ci,h,L,a,y,n0] = newcodesig (NO, l, num_paths, M, snr, chan, sig_pow_paths);
    [o1,d1,d2,d3,mf,m] = codesdhd (y, a, h, NO, Tm, Bd, M, B, n0);
    ...
  end
  ...
end
```

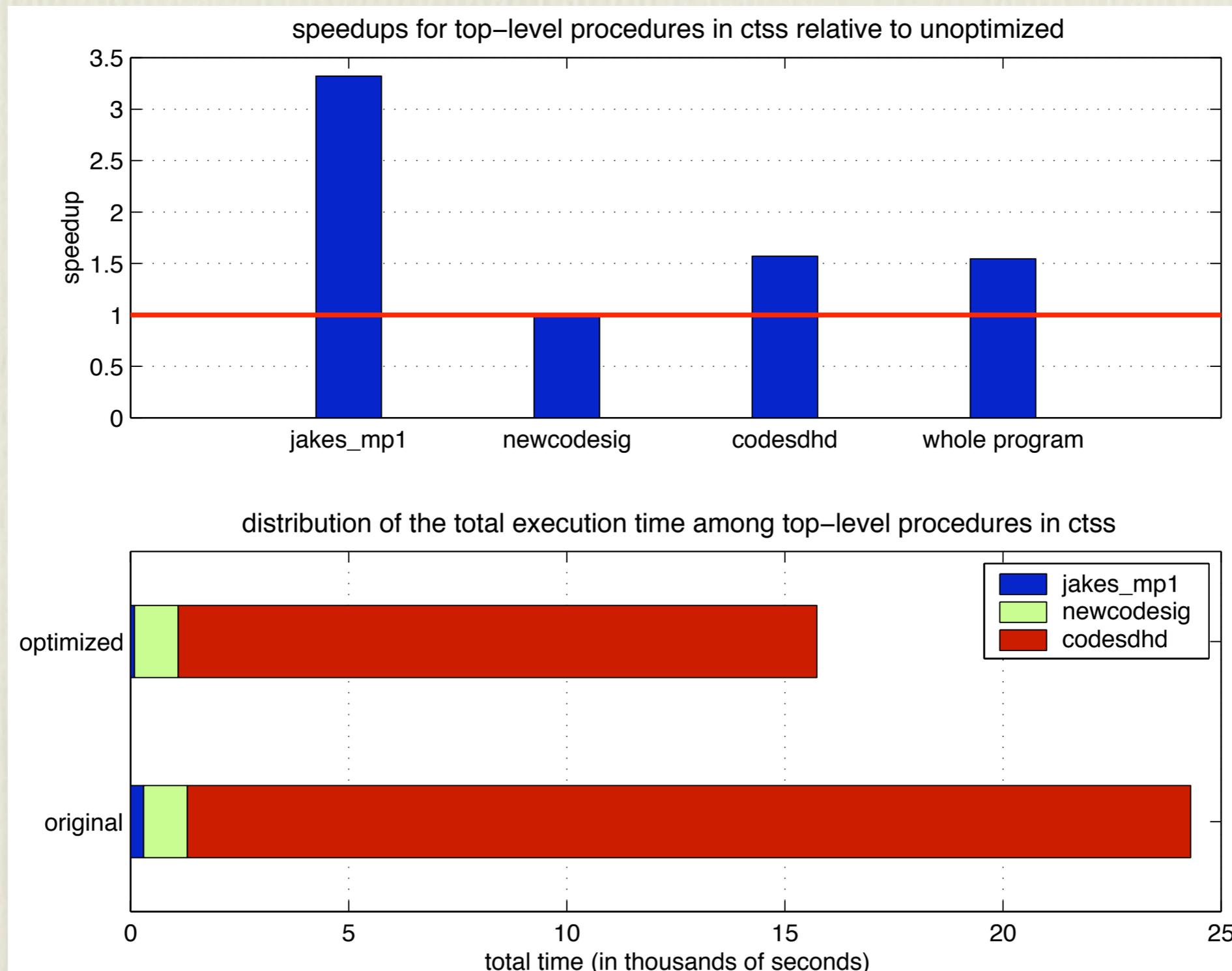
Optimizing Libraries

```
tmp = jakes_mp1_init (16500, 160, num_paths);  
for ii = 1:200  
    ...  
    chan = jakes_mp1_iter (ii, tmp);  
    ...  
    for snr = 2:2:20  
        ...  
        [s,x,ci,h,L,a,y,n0] = newcodesig (NO, l, num_paths, M, snr, chan, sig_pow_paths);  
        [o1,d1,d2,d3,mf,m] = codesdhd (y, a, h, NO, Tm, Bd, M, B, n0);  
        ...  
    end  
    ...  
end
```

Optimizing Libraries

```
tmp1 = jakes_mp1_init (16500, 160, num_paths);  
[h,L,tmp2] = newcodesig_init_1 (NO, l, num_paths, M, sig_pow_paths);  
[m, tmp3] = codesdhd_init (a, h, NO, Tm, Bd, M);  
for ii = 1:200  
    ...  
    chan = jakes_mp1_iter (ii, tmp1);  
    ...  
    [a, tmp4] = newcodesig_init_2 (chan, tmp2);  
    for snr = 2:2:20  
        ...  
        [s,x,ci,y,n0] = newcodesig_iter (snr, tmp4);  
        ...  
        [o1,d1,d2,d3,m] = codesdhd_iter (y, tmp3);  
        ...  
    end  
    ...  
end
```

Procedure Strength Reduction



Library Identities

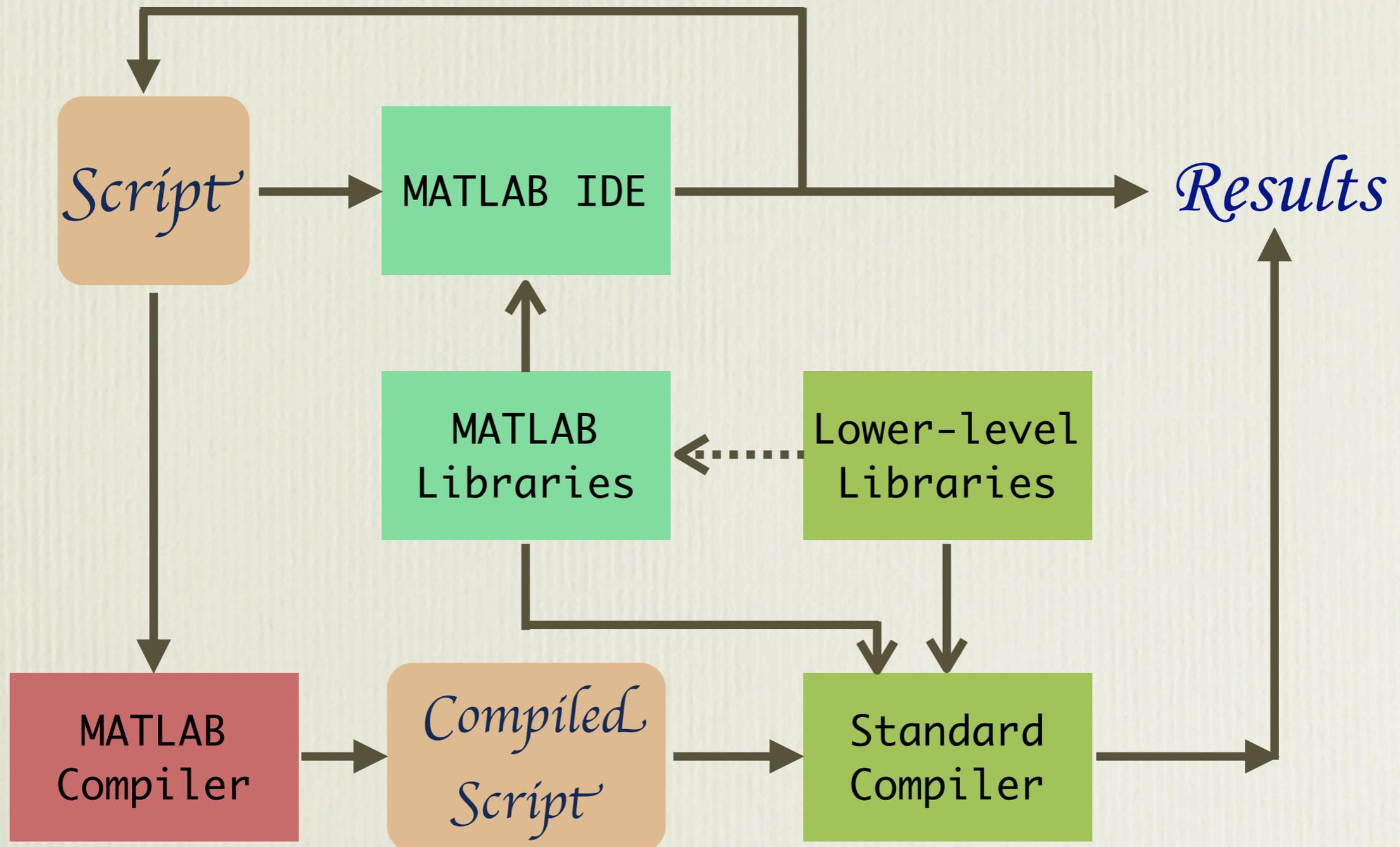
```
function [s, r, j_hist] = min_sr1 (xt, h, m, alpha)
...
while ~ok
...
  invsr = change_form_inv (sr0, h, m, low_rp);
  big_f = change_form (xt-invsr, h, m);
...
  while iter_s < 3*m
    ...
    invdr0 = change_form_inv (sr0, h, m, low_rp);
    sssdr = change_form (invdr0, h, m);
    ...
  end
...
  invsr = change_form_inv (sr0, h, m, low_rp);
  big_f = change_form (xt-invsr, h, m);
...
  while iter_r < n1*n2
    ...
    invdr0 = change_form_inv (sr0, h, m, low_rp);
    sssdr = change_form (invdr0, h, m);
    ...
  end
...
end
```

Lessons

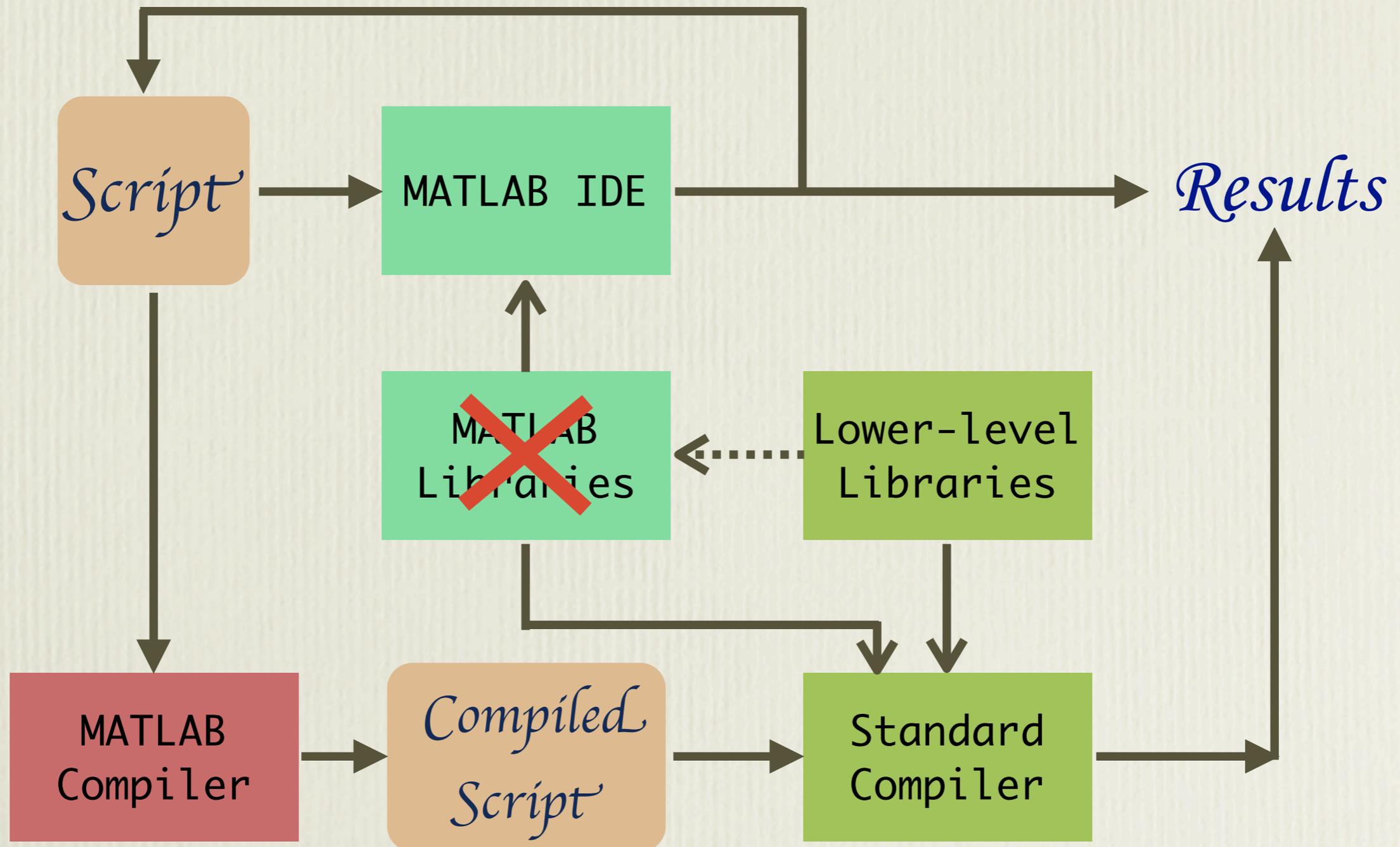
Two Types of Lessons

- Computer science
 - compilation (top-down vs bottom-up)
 - type inference strategy
- Software engineering
 - high-level compiler development

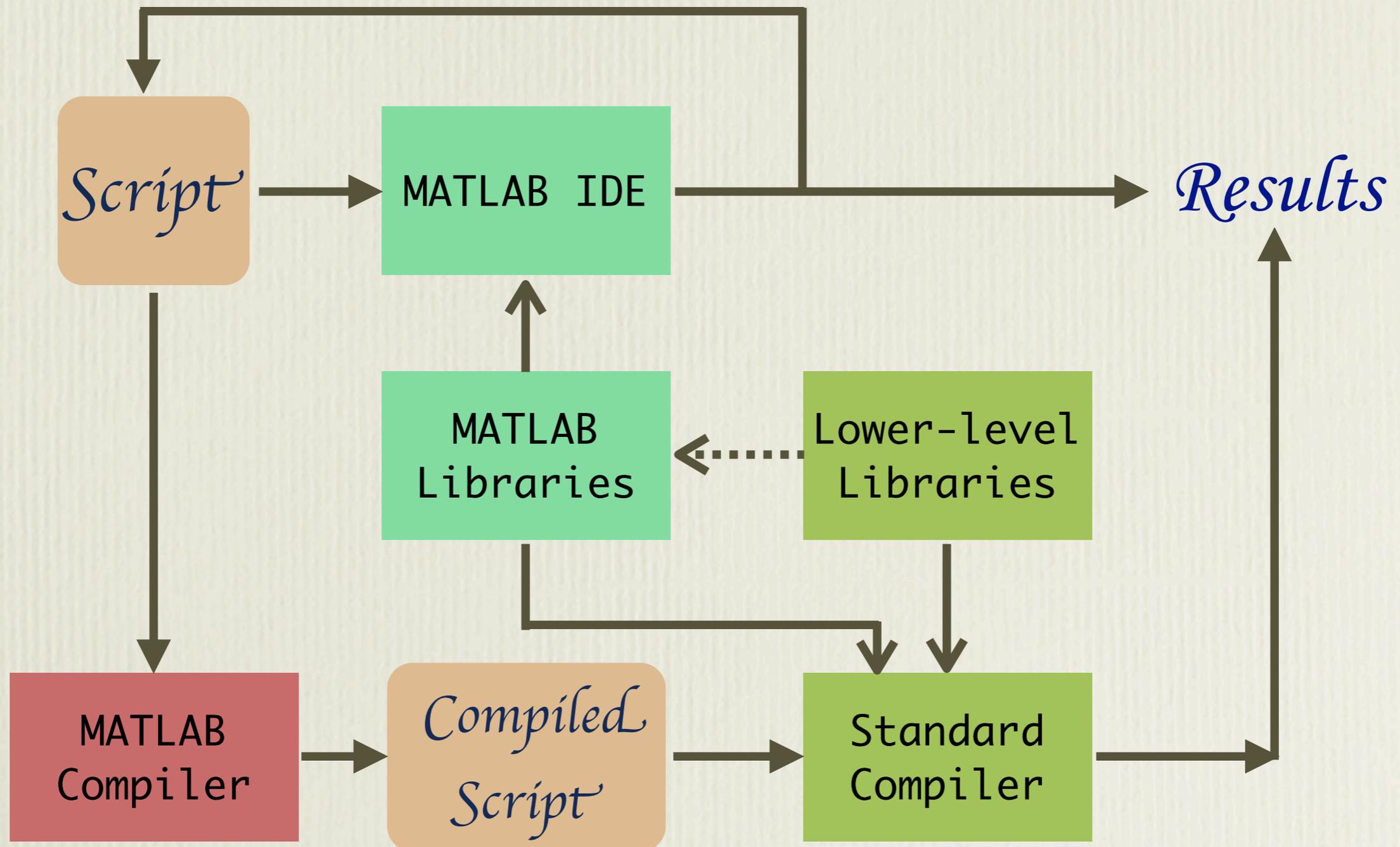
Compilation Strategy



Compilation Strategy



Compilation Strategy



Type Inference

Type = (intrinsic type, array size)

intrinsic type = integer, real, complex, etc.

array size = <d₁, d₂, d₃, ...>

- Heavily overloaded operators
 - backward propagation of very limited use
- Rich array subscripting semantics
 - arrays as subscripts
 - dynamically resizable arrays
 - “end” keyword

Subscripting in *MATLAB*

- Standard subscripting
 - $A(i_0)$, $A(j+1, i)$, $A(B(i))$
 - $A(1:100)$
- *MATLAB* subscripts: above plus ...
 - $A(B)$, $A(B,C)$ where B and C are arrays
 - $A(\text{end})$, $A(\text{end}+2)$
 - $A(x, y)$ where A is a 3-D array

Type Inference: Solution

- Program transformation-based strategy
 1. Expose type disambiguation in source language
 2. Evaluate types through concrete interpretation
- Advantages
 - Availability of the power of MATLAB

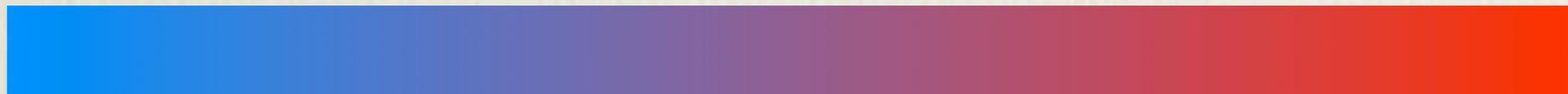
```
z(1:2:end, 1:2:end, 1:2:end) = zn;  
z = dlaplacian(z, [1, 1/2, 1/4, 1/8]);  
z = z(1:end-2, 1:end-2, 1:end-2);
```

```
a_0 = Param_compute_end_val(Param_size_z, 3, 1);
b_0 = Param_compute_end_val(Param_size_z, 3, 2);
c_0 = Param_compute_end_val(Param_size_z, 3, 3);
z(1:2:a_0, 1:2:b_0, 1:2:c_0) = zn;
d_0 = 1 / 2;
e_0 = 1 / 4;
f_0 = 1 / 8;
z = dlaplacian(z, [1, d_0, e_0, f_0]);
h_0 = g_0 - 2;
g_0 = Param_compute_end_val(Param_size_z, 3, 1);
j_0 = i_0 - 2;
i_0 = Param_compute_end_val(Param_size_z, 3, 2);
l_0 = k_0 - 2;
k_0 = Param_compute_end_val(Param_size_z, 3, 3);
z = z(1:h_0, 1:j_0, 1:l_0);
```

Type Inference: Solution

- Program transformation-based strategy
 1. expose type disambiguation in source language
 2. evaluate types through concrete interpretation
- Advantages
 - availability of the power of MATLAB
 - continuous spectrum of possibilities

completely static
(TeleGen)



completely dynamic
(MATLAB)

Engineering

- C++ as the language of choice
 - wide availability
 - “portable”
 - modular (?)
- A “high-level” language for writing compilers
 - Stratego (University of Utrecht, the Netherlands)

Status and Plan

Compiler Implementation

- Moved infrastructure to Stratego
 - shared with Ohio-State, Rice, UCSB
- Robust handling of difficult subscripting cases
 - exception: cell subscripting
- Type inference
 - exception: cells, structs

Plan: Compiling MATLAB

- Implement the hybrid compilation strategy
- Identify libraries
 - C++ generics or C / Fortran
 - ▶ study undertaken by Youngsang to evaluate the performance tradeoffs
 - Octave, Andrew Lumsdaine's concepts-based
- Implement “high-level” transformations
 - annotation language

Plan: Parallelizing MATLAB

- Model: distributed data
 - distributed data \Rightarrow parallel operations
 - replicated data \Rightarrow sequential operations
- Implementation
 - dependence analysis
 - cost-based analysis of data distributions
 - library development

Thank You