A Case Study of a Combinator-Based Compiler for a Language with Blocks and Recursive Functions

Marek J. Lao

Computer Science Department Indiana University Lindley Hall 101 Bloomington, IN 47405

TECHNICAL REPORT NO. 150

A Case Study of a Combinator-Based Compiler for a Language with Blocks and Recursive Functions

by

Marek J. Lao

October, 1983

Research reported herein was supported in part by a Fulbright Fellowship and by the National Science Foundation under grant numbers MCS 79-04183 and MCS 83-03325.



1 Introduction

This paper presents a target machine and a compiler developed by transforming the denotational semantics of a language. The method has been originally used by Wand in [4]. It consists of the following steps:

- elimination of λ-variables from the semantic equations through the introduction of special-purpose combinators,
- since the combinators have some associative properties, a combinator tree can be rotated into an almost linear form,
- distributive properties of the combinators make it possible to distribute the symbol table information into instructions, the resulting code becomes more linear and resembles a code for a conventional machine,
- after some representation decisions, a target machine to interpret the code is built.

The method has been used for an applicative language ([4]) and a simple block-structured language ([3]). The source language chosen for this paper is a block-structured language with recursive functions. We are not concerned with syntactic issues, therefore an abstract syntax resembling the one of parse trees has been chosen for the purpose of this paper.

Our main concern is the parameter passing and storage management. We discuss parameters called by function, variable, value and result. These modes can be easily extended by introducing the inout mode from Ada. Adding the call-by-name mechanism will require some additional work.

A sample program studied thoroughly in this paper is the following one:

In the declaration of the function:

- f is the name of the function,
- i and j are the names of local variables for parameters,
- value and result are the modes for passing these parameters, notice that
 the value assigned to i as a result parameter is overwritten in the assignment

statement,

- result is a standard variable storing the result of the function call.

The language is presented in Section 2. Sections 3 and 4 introduce the combinators to linearize the code and discuss their basic properties. Section 5 shows the static scoping and a way to bind identifiers at compile time. Then in Section 6 we present the first target machine, which is a version of a stack-display machine. We modify the compiler in Section 7 to produce somewhat more conventional code for a machine which uses Dijkstra's display mechanism ([1]).

2 Source language

The language we have chosen for this paper is presented in Tables 1-5. Due to its complexity, we owe the reader some explanations. First of all, we assume that nonterminals with indices have exactly the same syntax and meaning as those without. (Ident), (Const) and empty have the usual syntax and meaning. Operation symbols, i.e. (Binop), (Unop), (Binpred) and (Unpred), also remain unspecified throughout the paper. The main reason for introducing operation symbols to the language instead of pre-declared functions is to show the possibility of "optimized" code generation for parameter passing. The mechanism is different from the one used for applications because parameters of operations are always passed by (expressed) values.

```
(Program) ::= (Block)
             (Block) ::= (block (Dec)(Stmt-list))
                (Dec) ::= (Var-dec) | (Fun-dec) | empty
         \begin{array}{ll} \langle \mathit{Var-dec} \rangle ::= \big( \mathit{var} \langle \mathit{Ident} \rangle_1 \dots \langle \mathit{Ident} \rangle_n \big) & (n \geq 1) \\ \langle \mathit{Fun-dec} \rangle ::= \big( \mathit{fun} \langle \mathit{Ident} \rangle \big( \langle \mathit{Ident} \rangle_1 \dots \langle \mathit{Ident} \rangle_n \big) \big( \mathit{Mode-list-body} \big) \end{array}
                                                                                                                        (n \geq 0)
(Mode-list-body) ::= ((Mode-list))(Stmt-list)
       (Mode-list) ::= (In-mode)(Mode-list) | (Out-mode)(Mode-list) | empty
         (In-mode) ::= var | value | fun
      (Out-mode) ::= result
         (Stmt-list) ::= (Stmt)(Stmt-list) | empty
              (Stmt) ::= (skip) | (assign(Lhs)(Exp)) | (if(Boolexp)(Stmt)_1(Stmt)_2) |
                                  (while (Boolezp)(Stmt)) | (read(Lhs)) | (print(Ezp)) | (Block)
                (Lhs) ::= (Ident)
                (Exp) ::= (Lhs) | (Rexp)
              \langle Rezp \rangle ::= \langle Const \rangle \mid (\langle Binop \rangle \langle Ezp \rangle_1 \langle Ezp \rangle_2) \mid (\langle Unop \rangle \langle Ezp \rangle) \mid (\langle Fun \rangle \langle Apar-list \rangle)
                (Fun) ::= (Ident)
        (Apar-list) ::= (Apar)(Apar-list) | empty
              (Apar) ::= (Ident) | (Rexp)
          (Boolexp) ::= ((Binpred)(Exp)_1(Exp)_2) | ((Unpred)(Exp))
```

Table 1. Syntax of the source language

We concentrate on semantic questions. Therefore we do not check whether identifiers in a list are distinct; we assume that they are. For the same reason, we do not check whether the number of formal parameters and the number of modes for passing them are equal. Both these problems may be solved, for instance, by using a two-level grammar (as for Algol 68). Thus the questions are of a syntactic nature, and these features may be checked by a parser for our language. The syntax of declarations does not contain any type specification; we assume that all variables and functions are of the basic type, type integer.

In order to simplify semantic equations, we distinguish different occurrences of identifiers. An identifier used in an expression or actual parameter may mean:

- an expression (value),
- a variable passed to a function,
- a function passed to another function.

Since all these occurrences imply different actions to be done, it is reasonable to introduce different categories in the syntax already. Therefore we have three nonterminals, i.e. (Rexp), (Exp) and (Apar), describing expressions. An identifier used in (Exp) always means a value stored in a variable, while an identifier used in (Apar) may mean not only a value or a variable but also a function. The precise meaning in the latter case cannot be determined during compilation because formal functions, which do not specify their parameters, are allowed (see discussion in Sec. 8).

For the same reason, we introduce (Mode-list-body). The action for a parameter is carried out before ((In-mode) parameter) or after ((Out-mode) parameter) evaluating the function body (cf. [2]). Therefore semantic equations for parameter passing must consider the function body as well.

Basic domains

```
Maga
                                                       messages
     \boldsymbol{R}
                                                       truth values (\beta)
     N
                                                       integers - basic values
     E
                                                       expressed values (v)
     A
            = E^{*} \times Maga
                                                       answers
                                                       locations (1)
            = L + F
                                                       denoted values
     D
     \overline{D}
            = D + 'undeclared'
      V
            = E + D
                                                       storable values (v)
     \overline{V}
            = V + 'unused' + 'uninitialized'
            = Ec \rightarrow V^n \rightarrow K
                                                         (n \geq 0)
             = F_0 + F_1 + F_2 + \cdots
                                                       function values (f)
                                                       environments (\rho)
     Env = \langle Ident \rangle \rightarrow \overline{D}
            = E^{\bullet} \times E^{\bullet} \times [L \to \overline{V}]
                                                       states (\sigma)
                                      Continuations
     K
               = S \rightarrow A
                                         command continuations (x)
      Envc_n = Env \rightarrow L^n \rightarrow K declaration continuations (\chi) (n \ge 0)
               = E \rightarrow K
                                         expression continuations
      Be
               = B \rightarrow K
                                         boolean expression continuations
               = L \rightarrow K
                                         L-value continuations
     Le
     Fe
               = F \rightarrow K
                                          F-value continuations
               = \overline{V} \rightarrow K
                                          V-value continuations
      Ve
               = \overline{D} \rightarrow K
     De
                                         D-value continuations
               = V^n \to K
                                         parameter passing continuations
     Pen
A product of P^n is meant to be curried, i.e. P^n \to X = P \to \cdots \to P \to X
```

Table 2. Semantic domains

The first component of state S corresponds to the state of the input tape; the second, to the state of the output tape. The function $L \to \overline{V}$ describes the state of the memory. The domain F_n consists of all n-parameter functions; V^n in its definition is a vector of parameters. Parameters passed to a function are temporarily stored under the locations of local variables. So L^n in the definition of $M\ell_n$ is a vector of the locations

where the parameters have been stored and where their values (modified accordingly to the modes) are to be stored lateron. L and V in the definition of the meaning functions for modes denote the location of the local variable and the value of the passed parameter respectively. Notice that the location is marked 'uninitialized' before the appriopriate action for $\langle In-mode \rangle$ or the function body is evaluated; it is especially important for $\langle Out-mode \rangle$ parameters.

In all semantic equations, we have assumed a standardized form of semantic functions which takes the environment as an argument. This makes it shorter and easier to change the semantic equations into a combinatorial form (compare with [3], [4]). Therefore the functions giving the meaning of constants, operators and modes require the environment. Their actions do not depend on its value, though.

```
P: (Program) \rightarrow S \rightarrow A
B\ell: (Block) \to Env \to K \to K
D_n: (Dec) \to Env \to Env c_n \to K
                                                              (n \geq 0)
S\ell: (Stmt-list) \rightarrow Env \rightarrow K \rightarrow K
S: (Stmt) \rightarrow Env \rightarrow K \rightarrow K
R: \langle Exp \rangle \rightarrow Env \rightarrow Ec \rightarrow K
C: (Const) \rightarrow Env \rightarrow Ec \rightarrow K
L: (Lhs) \rightarrow Env \rightarrow Lc \rightarrow K
B: (Boolezp) \rightarrow Env \rightarrow Bc \rightarrow K
\mathcal{F}: \langle Fun \rangle \to Env \to Fc \to K
M\ell_n: (Mode-list-body) \to Env \to L^n \to K \quad (n \ge 0)
A\ell_n: (Apar-list) \to Env \to Pc_n \to K \qquad (n \ge 0)
A: \langle Apar \rangle \rightarrow Env \rightarrow Ve \rightarrow K
M_{in}: (In-mode) \rightarrow Env \rightarrow K \rightarrow L \rightarrow V \rightarrow K
M_{out}: (Out\text{-}mode) \rightarrow Env \rightarrow K \rightarrow L \rightarrow V \rightarrow K
O_h: (Binop) \to Env \to Ec \to E \to E \to K
O_u : \{Unop\} \to Env \to Ec \to E \to K
O_{bp}: \langle Binpred \rangle \to Env \to Bc \to E \to E \to K
O_{up}: \{Unpred\} \rightarrow Env \rightarrow Bc \rightarrow E \rightarrow K
```

Table 3. Meaning functions

The basic kind of a block is a declaration of variables and a list of statements to be evaluated in the new environment containing these variables. We have decided that after the evaluation of the statement list in a block, the locations of its variables are released. Therefore the continuation for the statements is of the form $release-block_n \rho' l_1 \dots l_n \kappa$ and the declaration continuation requires the vector of the new locations. This shows us that a stack-wise implementation of the memory is possible.

As we have already noticed, the meaning of actual parameters must be determined by the applied function and, in the general case, it requires run-time checking. In order to have only one copy of the code that checks the correctness of actual parameters, we have decided to introduce a two-step application. The first step (A and $A\ell$) evaluates actual parameters to expressed values, if the parameter is (Rexp), and to denoted values for identifiers. The next step ($M\ell$) checks the correctness between actual parameters and the specification within the applied function. During this step dereferencing of the passed values is carried out if necessary. Thus the action for a var parameter (L-pass) stores the location of the passed variable in the local variable, for a fun parameter F-pass stores the F-value in the local variable. For a value parameter (E-pass), the local variable is initialized with the value of the expression; if a variable has been passed, it is

```
Programs
P[p] = \lambda \sigma_0.B\ell[p] init-env init-cont \sigma_0
                                                                                           Statements
S\ell[[empty]] = \lambda \rho \kappa.\kappa
S\ell[s \ el] = \lambda \rho \kappa. S[s] \rho(S\ell[el] \rho \kappa)
S[(skip)] = \lambda \rho \kappa.\kappa
S[(assign id e)] = \lambda \rho \kappa. L[id] \rho(\lambda l. R[e] \rho(store \rho \kappa l))
S[[(if \ b \ s_1 \ s_2)]] = \lambda \rho \kappa. B[[b]] \rho(\lambda \beta. \beta \to S[[s_1]] \rho \kappa, S[[s_2]] \rho \kappa)
S[[(\mathbf{while}\ b\ s)]] = \lambda \rho \kappa . fix (\lambda \theta . B[[b]] \rho(\lambda \beta . \beta \to S[[s]] \rho \theta, \kappa))
S[(read id)] = \lambda \rho \kappa. L[id] \rho(\lambda l. do-read \rho(store \rho \kappa l))
S[[(print e)]] = \lambda \rho \kappa. R[[e]] \rho(\lambda v. do-print \rho \kappa v)
S[block] = B\ell[block]
                                                                                           Expressions
\mathcal{R}[\![id]\!] = \lambda \rho \eta. L[\![id]\!] \rho(fetch \rho \eta)
R[e] = C[e]
\mathcal{R}[\![(\bigoplus e_1 \ e_2)]\!] = \lambda \rho \eta. \mathcal{R}[\![e_1]\!] \rho(\lambda v_1. \mathcal{R}[\![e_2]\!] \rho(\lambda v_2. O_b[\![\bigoplus]\!] \rho \eta v_1 v_2))
\mathbb{R}[(\ominus e)] = \lambda \rho \eta . \mathbb{R}[e] \rho(\lambda v. O_u[\ominus]) \rho \eta v)
\mathcal{R} \llbracket (id \ a_1 \dots a_n) \rrbracket = \lambda \rho \eta. \mathcal{F} \llbracket id \rrbracket \rho (check_n \rho (\lambda f. \mathcal{A} \ell_n \llbracket a_1 \dots a_n \rrbracket \rho (\lambda v_1 \dots v_n. f \eta v_1 \dots v_n)))
B[\![(\prec e_1 \ e_2)]\!] = \lambda \rho \eta . \mathcal{R}[\![e_1]\!] \rho(\lambda v_1 . \mathcal{R}[\![e_2]\!] \rho(\lambda v_2 . O_{bp}[\![\prec]\!] \rho \eta v_1 v_2))
B[[(?e)]] = \lambda \rho \eta. R[[e]] \rho(\lambda v. O_{up}[[?]] \rho \eta v)
\mathcal{F}[\![id]\!] = \lambda \rho \eta.lookup[\![id]\!] \rho(\lambda v.v \in F \rightarrow \eta v, terminate[\!["not a function applied"]\!])
L[[id]] = \lambda \rho \eta.lookup[[id]] \rho(\lambda v.v \in L \to \eta v, terminate["not a variable"])
                                                                                     Actual parameters
Alo[[empty]] = \lambda \rho \eta. \eta
A\ell_n[a \ al] = \lambda \rho \eta. A[a] \rho(\lambda v. A\ell_{n-1}[al] \rho(\eta v))
A[id] = lookup[id]
A[e] = R[e]
                                                                                                Blocks
B\ell[(block \ sl)] = S\ell[sl]
\mathcal{B}\ell[(block\ (var\ id_1...id_n)\ sl)] = \lambda \rho \kappa. \mathcal{D}_n[(var\ id_1...id_n)] \rho(\lambda \rho' l_1...l_n. \mathcal{S}\ell[[sl]]\rho')
                                                                                                                                                  (release-block_n p'l_1 ... l_n \kappa))
B\ell[\![(block (fun \ \alpha) \ sl)]\!] = \lambda \rho \kappa. D_{\theta}[\![(fun \ \alpha)]\!] \rho(\lambda \rho'. S\ell[\![sl]\!] \rho' \kappa)
                                                                                   Variable declaration
D_n[[(var\ id_1...id_n)]] = \lambda \rho \chi \sigma. let(l_1,...l_n) = new_n \sigma, and \sigma' = adjoin_n \sigma l_1...l_n
                                                         in \chi(\rho[l_1/id_1]...[l_n/id_n])l_1...l_n\sigma'
                                                                                   Function declaration
\mathcal{D}_{O} \llbracket (\text{fun } id \ (id_{1} \dots id_{n}) \ (m_{1} \dots m_{n}) \ sl) \rrbracket = \lambda \rho \chi . \chi (\text{fiz } (\lambda \rho' . \llbracket (f \rho') / id \rrbracket))
 where f is:
f = \lambda \rho' \eta v_1 \dots v_n \sigma. let(l_0, l_1, \dots l_n) = new_{n+1} \sigma, and \rho'' = \rho' [l_0/result][l_1/id_1] \dots [l_n/id_n],
                                      and \sigma' = adjoin-init_{n+1}\sigma l_0 l_1 \dots l_n 'uninitialized' v_1 \dots v_n
                                      in M\ell_n[(m_1...m_n) \ sl\ ]\rho^nl_1...l_n(fetch\rho''(release-fun_{n+1}\rho''l_0l_1...l_n\eta)l_0)\sigma'
                                                                                     Parameter passing
M\ell_0[(empty) si] = S\ell[si]
\mathcal{M}\ell_{n} \llbracket (im \ ml) \ sl \rrbracket = \lambda \rho l_{1} \dots l_{n} \kappa \sigma. \mathcal{M}_{in} \llbracket im \rrbracket \rho (\mathcal{M}\ell_{n-1} \llbracket (ml) \ sl \rrbracket \rho l_{2} \dots l_{n} \kappa) l_{1} (\sigma_{3} l_{1})
                                                                                     \langle \sigma_1, \sigma_2, \sigma_8 ['uninitialized'/l_1] \rangle
\mathbb{M}\ell_n \llbracket (om\ ml)\ sl \rrbracket = \lambda \rho l_1 \dots l_n \kappa \sigma. \mathbb{M}\ell_{n-1} \llbracket (ml)\ sl\ \rrbracket \rho l_2 \dots l_n \big( \mathbb{M}_{out} \llbracket om \rrbracket \rho \kappa l_1 (\sigma_3 l_1) \big)
                                                                                                                   (\sigma_1, \sigma_2, \sigma_3 ['uninitialized'/l_1])
                                                                                                Others
                                                       O_b[\![\oplus]\!] = binop[\![\oplus]\!]
                                                                                                        0u[\Theta] = unop[\Theta]
C[c] = const[c]
O_{bp}[\![\prec]\!] = binpred[\![\prec]\!]
                                                                                                        Min [var] = L-pass
                                                       Oup [ ? ] = unpred [ ? ]
                                                                                                        Mout[result] = I-pass
Min [value] = E-pass
                                                      Min[fun] = F-pass
```

Table 4. Semantic equations

```
terminate[m] = \lambda \sigma.(\sigma_2 \mid m)
init-env = \lambda id. 'undeclared'
init-cont = terminate [ "normal termination"]
new_n = \lambda \sigma.some distinct (l_1, \dots l_n) such that (\sigma_S l_i) =  'unused'
adjoin_n = \lambda \sigma l_1 \dots l_n . (\sigma_1, \sigma_2, \sigma_3 ['uninitialized'/l_1] \dots ['uninitialized'/l_n])
adjoin-init_n = \lambda \sigma l_1 \dots l_n v_1 \dots v_n . (\sigma_1, \sigma_2, \sigma_3 [v_1/l_1] \dots [v_n/l_n])
release<sub>n</sub> = \lambda \sigma l_1 \dots l_n \cdot (\sigma_1, \sigma_2, \sigma_3 ['unused'/l_1] \dots ['unused'/l_n])
release-block_n = \lambda \rho l_1 \dots l_n \kappa \sigma . \kappa (release_n \sigma l_1 \dots l_n)
release-fun<sub>n</sub> = \lambda \rho l_1 \dots l_n \eta v \sigma . \eta v (release_n \sigma l_1 \dots l_n)
store = \lambda \rho \kappa [v\sigma.\kappa(\sigma_1, \sigma_2, \sigma_3[v/l])
do\text{-read} = \lambda \rho \eta \sigma. \sigma_1 = nil \rightarrow terminate [\text{"eof encountered"}] \sigma, \eta (first \sigma_1) (rest \sigma_1, \sigma_2, \sigma_3)
do\text{-print} = \lambda \rho \kappa v \sigma . \kappa (\sigma_1, \sigma_2 \parallel v, \sigma_8)
fetch = \lambda \rho \eta l\sigma.(\sigma_S l) = \text{`uninitialized'} \rightarrow terminate["unininitialized variable"]] \sigma, \eta(\sigma_S l)\sigma
check_n = \lambda \rho \eta f. f \in F_n \rightarrow \eta f, terminate ["wrong number of parameters"]
find[id] = \lambda \rho \eta. \eta(\rho id)
deref? = \lambda \rho \eta v \sigma . v \in L \rightarrow \eta(\sigma_S v) \sigma, \eta v \sigma
L-pass = \lambda \rho \kappa l v. v \in L \rightarrow store \rho \kappa l v, terminate ["not a variable passed"]
E-pass = \lambda \rho \kappa l v . deref ? \rho (\lambda v' . v' \in E \rightarrow store \rho \kappa l v', terminate ["not an expression passed"]) v
F-pass = \lambda \rho \kappa l v. v \in DF \rightarrow store \rho \kappa l v, terminate ["not a function passed"]
I-pass = \lambda \rho \kappa l v.v \in L \rightarrow fetch \rho(store \rho \kappa v)l, terminate ["not a variable passed for result"]
lookup[id] = \lambda \rho \eta .find[id] \rho(\lambda d\sigma .d = 'undeclared' \rightarrow terminate["undeclared identifier"]]\sigma,
                                                       d \in F \rightarrow \eta d\sigma,

    regular function

                                                       (\sigma_{\mathcal{S}} d) \in F \to \eta(\sigma_{\mathcal{S}} d)\sigma,
                                                                                                             -- fun parameter
                                                        (\sigma_s d) \in L \to \eta(\sigma_s d)\sigma,
                                                                                                               - var parameter
                                                        ndo)
```

Table 5. Auxiliary functions

dereferenced. For a result parameter (I-pass), the value assigned to the local variable (I) is stored under the passed location (v). The last action has to be done after evaluating the body; so I-pass'es are put on "the stack of continuations". Due to the order of parameters, the result parameters are assigned values from the right-hand side to the left. In our solution, the checking of the kind of a result parameter is done after evaluating the function body. Both the order of passing result parameters and the time of checking their kind can be easily changed.

Finally, let us discuss the equation for a function declaration. A function declaration itself changes the environment for the block and the function body only. The F-value in this new environment is quite complex. First of all, a function transfers its parameters to the locations of local variables (adjoin-init). Then the parameter passing and evaluating the function body ($M\ell$) are to be done; $l_1, \ldots l_n$ passed to $M\ell$ denote the locations of the local variables. The continuation for $M\ell$ consists of:

- fetching the value of the function call; every function possesses a (pre-declared) variable with the standard identifier result; the value assigned to this variable at the end of the evaluation of the function body becomes the value of the application*,
- releasing the locations of local variables (release-fun).

This idea comes from Loglan, a programming language designed and implemented at the Institute of Informatics, the University of Warsaw, Poland

Now we present two examples to be discussed in the paper.

Example 1

The following program will illustrate static scoping and the implementation of a loop:

The answer is, of course, the value of i from the outer block. The operators of positive? and minus 1 have the natural semantics.

Example 2

The following program contains a recursive function to compute the factorial of its first parameter. The other parameter is to illustrate the result mode.

The answer should be 1, i.e. the value of the factorial, despite the fact that i occurs as a result parameter and is assigned the value of 0 as well.

3 Combinatorial semantic equations

Now we rewrite the semantic equations eliminating λ -variables. The additional auxiliary functions are shown in Table 6. The equations are modified by the introduction of special-purpose combinators:

```
- a family of sequencing combinators (cf. [4])
D_n(\alpha, \beta) = \lambda \rho x_0 x_1 \dots x_n . \alpha \rho(\beta \rho x_0 x_1 \dots x_n)
```

```
\begin{aligned} \operatorname{return} &= \lambda \rho \kappa. \kappa \\ \operatorname{test} f g &= \lambda \rho \kappa. \beta. \beta \to f \rho \kappa, g \rho \kappa \\ \operatorname{wloop} f &= \lambda \rho \kappa. \operatorname{fiz} (f \rho \kappa) \\ \operatorname{wtest} f &= \lambda \rho \kappa. \theta. \beta. \beta \to f \rho \theta, \kappa \\ \operatorname{table}_0 &= \operatorname{init-env} \\ \operatorname{ext}_n & \operatorname{id}_n \dots \operatorname{id}_1 &= \lambda \rho l_1 \dots l_n \cdot \rho [l_1/\operatorname{id}_1] \dots [l_n/\operatorname{id}_n] \\ \operatorname{block}_n f &= \operatorname{env} &= \lambda \kappa \sigma. \operatorname{let} (l_1, \dots l_n) &= \operatorname{new}_n \sigma \text{ and } \sigma' &= \operatorname{adjoin}_n \sigma l_1 \dots l_n \\ & & \operatorname{in} f (\operatorname{env} l_1 \dots l_n) l_1 \dots l_n \kappa \sigma' \\ \operatorname{ext-fun} & \operatorname{id} f &= \lambda \rho. \operatorname{fiz} (\lambda \rho'. \rho [(f \rho')/\operatorname{id}]) \\ \operatorname{function}_n f &= \operatorname{env} &= \lambda \eta v_1 \dots v_n \sigma. \operatorname{let} (l_0, l_1, \dots l_n) &= \operatorname{new}_n \sigma \\ & & \operatorname{and} \sigma' &= \operatorname{adjoin-init}_{n+1} \sigma l_0 l_1 \dots l_n '\operatorname{uninitialized}' v_1 \dots v_n \\ & & \operatorname{in} f (\operatorname{env} l_0 l_1 \dots l_n) l_1 \dots l_n l_0 l_1 \dots l_n \eta l_0 \sigma' \\ \operatorname{pass}_n f &= \lambda \rho a_0 a_1 \dots a_n \sigma. f \rho a_1 \dots a_n a_0 (\sigma_3 a_0) (\sigma_1, \sigma_2, \sigma_3 ['\operatorname{uninitialized}'/a_0]) \\ \operatorname{apply}_n &= \lambda \rho \eta f v_1 \dots v_n. f \eta v_1 \dots v_n \end{aligned}
```

Table 6. Additional auxiliary functions

```
    a family of binding combinators (cf. [4],[5])
    B<sub>p</sub>(α, β) = λa<sub>1</sub>...a<sub>p</sub>.α(βa<sub>1</sub>...a<sub>p</sub>)
    a family of generalized D's ("post" combinators)
    P<sub>mn</sub>(α, β) = λρa<sub>1</sub>...a<sub>m</sub>x<sub>0</sub>x<sub>1</sub>...x<sub>n</sub>.αρa<sub>1</sub>...a<sub>m</sub>(βρx<sub>0</sub>x<sub>1</sub>...x<sub>n</sub>)
    a transferring combinator
    T(α) = λρην.αρ(ην)
```

The D and B combinators have been presented and discussed by Wand in [4], [5]. In the original version, D was always used with a continuation in place of x_0 . Here we use this combinator in a little different way; we know that one of the x's is a continuation. It does not, however, change any of the properties of D discussed in [4].

The P combinators generalize D's in the sense that some of their parameters are bound to the first argument while the rest to the second. These combinators are extensively used in the equations for parameter passing. While the combinator tree is rotated, however, the combinators become of the form of P_{0n} which is equivalent to D_n . Here also one of the x's is a continuation. In our applications, a's are the locations of formal parameters passed to the function body (α) ; x's are the parameters for passing results to the calling module as well as releasing locations, that is β corresponds to the action to be done after evaluating the function body, I-pass, fetch, release-fun.

The T combinator, due to Wand, transfers a value passed as a parameter onto the stack for continuation. Similarly to P, it disappears while the combinator tree is being linearized.

Now using the combinators and auxiliary functions we are able to rewrite the semantic equations without λ -variables. The results are shown in Table 7. Notice that checking whether an identifier has been declared can be done during compilation. It is also possible to determine the kind of an identifier at the same time. Therefore, the equations for $\mathcal{L}[id]$, $\mathcal{F}[id]$ and $\mathcal{A}[id]$ are reduced to lookup[id].

```
S\ell[[empty]] = return
S\ell[sl\ sl] = D_0(S[s], S\ell[sl])
S[(skip)] = return
S[(assign id e)] = D_0(L[id], D_1(R[e], store))
S[(if \ b \ s_1 \ s_2)] = D_0(B[b], test \ S[s_1] \ S[s_2])
S[(while \ b \ s)] = wloop \ D_1(B[b], wtest \ D_0(S[s], return))
S[[(read id)]] = D_0(L[id], D_1(do-read, store))
S[[print e]] = D_0(R[e], do-print)
S[block] = B\ell[block]
\mathbb{R}[id] = D_0(\mathbb{L}[id], fetch)
R[c] = const[c]
\mathcal{R}[\![(\oplus e_1 e_2)]\!] = D_0(\mathcal{R}[\![e_1]\!], D_1(\mathcal{R}[\![e_2]\!], binop[\![\oplus]\!]))
\mathbb{R}[(\ominus e)] = D_0(\mathbb{R}[e], unop[\ominus])
\mathcal{R}\llbracket(id\ a_1\ldots a_n)\rrbracket = D_0(\mathcal{F}\llbracket id\rrbracket, D_0(check_n, D_1(\mathcal{A}\ell_n\llbracket a_1\ldots a_n\rrbracket, apply_n))
B[(\prec e_1 \ e_2)] = D_0(R[e_1], D_1(R[e_2], binpred[\![\prec]\!]))
B[(?e)] = D_0(R[e], unpred[?])
L id = lookup id
f [id] = lookup [id]
Alo[[empty]] = return
A\ell_n \llbracket a \ a \ell \rrbracket = D_0(A \llbracket a \rrbracket, T(A\ell_{n-1} \llbracket a \ell \rrbracket))
A [id] = lookup [id]
A[e] = R[e]
Be [[ block al] = Se [al]
B\ell[(block (var id_1...id_n) sl)] = B_1(block_n D_n(S\ell[sl], release-block_n), ext_n id_n...id_1)
\mathcal{B}\ell[\![(\operatorname{block}\ (\operatorname{fun}\ id\ (id_1\ldots id_n)\ (ml)\ sl_1)\ sl_2)\ ]\!] = B_1(\mathcal{S}\ell[\![sl_2]\!],\operatorname{ext-fun}\ id\ f)
        f = B_1(function_n P_{nn+2}(M\ell_n[(ml) sl_1], D_{n+1}(fetch, release-fun_{n+1})), ext_{n+1} id_n...id_1 result)
Ml_0[(empty) sl] = Sl[sl]
\mathsf{M}\ell_{n}\llbracket(\mathit{im}\ \mathit{ml})\ \mathit{sl}\rrbracket = \mathit{pass}_{n}(D_{n-1}(\mathit{M}_{\mathit{in}}\llbracket\mathit{im}\rrbracket, \mathit{M}\ell_{n-1}\llbracket(\mathit{ml})\ \mathit{sl}\rrbracket))
\mathcal{M}\ell_n \llbracket (om\ ml)\ sl \rrbracket = pass_n (P_{n-1} 2(\mathcal{M}\ell_{n-1} \llbracket (ml)\ sl \rrbracket, \mathcal{M}_{out} \llbracket om \rrbracket))
```

Table 7. Combinatorial form of semantic equations

Since the modification of the equations is generally not difficult, we present the required transformations for only a few of them.

The equation for a block declaring variables may be modified as follows:

```
\begin{split} \mathcal{B}\ell[\![\![\!] \mathbf{block} \; (\mathbf{var} \; id_1 \dots id_n) \; sl)\!] \\ &= \lambda \rho \kappa. D_n[\![\![\![\!] \mathbf{var} \; id_1 \dots id_n)]\!] \rho(\lambda \rho' l_1 \dots l_n. D_n(\mathcal{S}\ell[\![\![\!] \mathbf{sl}]\!], release-block_n) \rho' l_1 \dots l_n \kappa) \\ &= \lambda \rho \kappa \sigma. let \; (l_1, \dots l_n) = new_n \sigma \; and \; \sigma' = adjoin_n \sigma l_1 \dots l_n \\ &\quad in \; D_n(\mathcal{S}\ell[\![\![\![\!] \mathbf{sl}]\!], release-block_n) (\rho[l_1/id_1] \dots [l_n/id_n]) l_1 \dots l_n \kappa \sigma' \\ &= \lambda \rho. [\lambda env \kappa \sigma. let \; (l_1, \dots l_n) = new_n \sigma \; and \; \sigma' = adjoin_n \sigma l_1 \dots l_n \\ &\quad in \; D_n(\mathcal{S}\ell[\![\![\![\!\![\!\!] \mathbf{sl}]\!], release-block_n) (env \; l_1 \dots l_n) l_1 \dots l_n \kappa \sigma'] \; (ext_n id_n \dots id_n \rho) \\ &= \lambda \rho. block_n D_n(\mathcal{S}\ell[\![\![\!\![\!\![\!\!] \mathbf{sl}]\!], release-block_n) (ext_n \; id_n \dots id_1 \rho) \\ &= B_n(block_n \; D_n(\mathcal{S}\ell[\![\!\![\!\![\!\![\!\!] \mathbf{sl}]\!], release-block_n)), ext_n \; id_n \dots id_1) \end{split}
```

The transformations required for a function declaration are more complicated and are defined below:

$$D_0[[fun id (id_1...id_n) (ml) sl)]] = \lambda \rho \chi.\chi((ext-fun idf)\rho)$$

where f is:

```
f = \lambda \rho' \eta v_1 \dots v_n \sigma.let (l_0, l_1, \dots l_n) = new_{n+1} \sigma \text{ and } \rho'' = \rho'[l_0/result][l_1/id_1] \dots [l_n/id_n]
and \sigma' = adjoin-init_{n+1} \sigma l_0 l_1 \dots l_n \text{ `uninitialized '} v_1 \dots v_n
in \ \mathcal{M}\ell_n [\![(ml)\ s\ell]\!] \rho'' l_1 \dots l_n (fetch\rho'' (release-fun_{n+1} \rho'' l_0 l_1 \dots l_n \eta) l_0) \sigma'
```

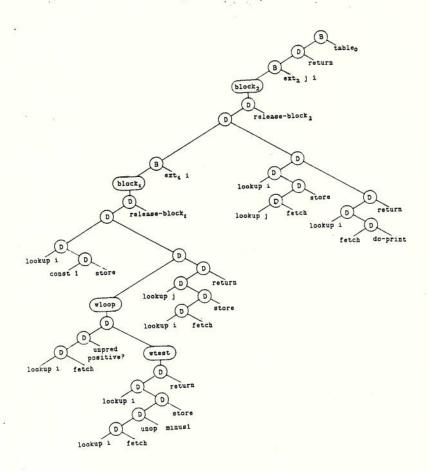


Figure 1. Example 1 - the "naive" code

```
=\lambda\rho'\eta v_1\dots v_n\sigma.let\left(l_0,l_1,\dots l_n\right)=new_{n+1}\sigma\ and\ \rho''=\rho'[l_0/result][l_1/id_1]\dots[l_n/id_n]
                          and \sigma' = adjoin-init_{n+1}\sigma l_0 l_1 \dots l_n 'uninitialized' v_1 \dots v_n
                         in M\ell_n[(ml) s f] \rho'' l_1 \dots l_n(D_n(fetch, release-fun_{n+1}) \rho'' l_0 l_1 \dots l_n \eta l_0) \sigma'
=\lambda\rho'\eta v_1\dots v_n\sigma.let\left(l_0,l_1,\dots l_n\right)=new_{n+1}\sigma \ and \ \rho''=\rho'[l_0/result][l_1/id_1]\dots[l_n/id_n]
                          and \sigma' = adjoin-init_{n+1}\sigma l_0 l_1 \dots l_n 'uninitialized' v_1 \dots v_n
                          in P_{n,n+2}(M\ell_n[(ml) sl], D_{n+1}(fetch, release-fun_{n+1}))
                                         \rho'' l_1 \dots l_n l_0 l_1 \dots l_n \eta l_0 \sigma'
 that is
f = \lambda \rho' \cdot function_n P_{n n+2}(M\ell_n[(ml) sl], D_{n+1}(fetch, release-fun_{n+1}))
                                (ext_{n+1} id_n ... id_1 result \rho')
  =B_1(function_n P_{n\,n+2}(\mathcal{M}\ell_n[(ml) \,s], D_{n+1}(fetch, release-fun_{n+1})),
            ext_{n+1} id_n \dots id_1 result
 And then combining these results together with the definition of a block, we have:
 \mathcal{B}\ell[(block (fun id (id_1...id_n) (ml) sl_1) sl_2)]]
        = \lambda \rho \kappa. S \ell \llbracket sl_2 \rrbracket ((ext-fun \ id \ B_1(function_n...)\rho) \kappa
       = B_1(S\ell[sl_2], ext-fun id B_1(function_n...))
```

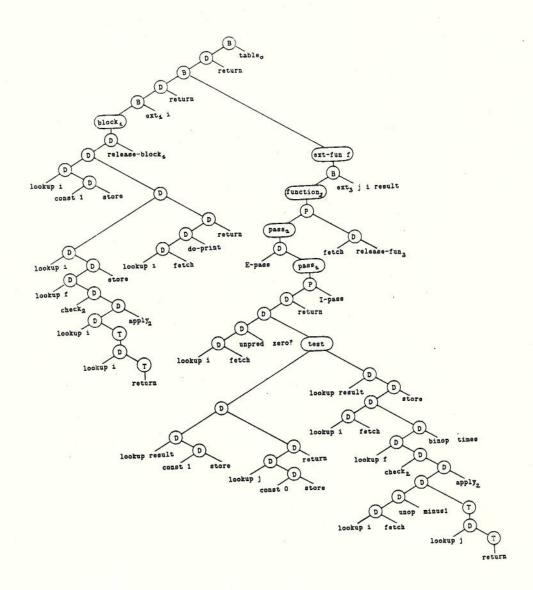


Figure 2. Example 2 - the "naive" code

The modifications of the equations for parameter passing are straightforward:

$$\begin{split} \mathcal{M}\ell_{n} & \llbracket (im\ ml)\ s\ell \rrbracket \\ &= \lambda \rho l_{1} \dots l_{n} \kappa \sigma. \mathcal{M}_{in} \llbracket im \rrbracket \rho \big(\mathcal{M}\ell_{n-1} \llbracket (ml)\ s\ell \rrbracket \rho l_{2} \dots l_{n} \kappa \big) l_{1} \big(\sigma_{3}\ l_{1} \big) \\ &\qquad \qquad (\sigma_{1}, \sigma_{2}, \sigma_{3} \llbracket 'uninitialized'/l_{1} \rrbracket \big) \\ &= \lambda \rho l_{1} \dots l_{n} \kappa \sigma. D_{n-1} \big(\mathcal{M}_{in} \llbracket im \rrbracket, \mathcal{M}\ell_{n-1} \llbracket (ml)\ s\ell \rrbracket \big) \rho l_{2} \dots l_{n} \kappa l_{1} \big(\sigma_{3}\ l_{1} \big) \\ &\qquad \qquad (\sigma_{1}, \sigma_{2}, \sigma_{3} \llbracket 'uninitialized'/l_{1} \rrbracket \big) \\ &= pass_{n}\ D_{n-1} \big(\mathcal{M}_{in} \llbracket im \rrbracket, \mathcal{M}\ell_{n-1} \llbracket (ml)\ s\ell \rrbracket \big) \big) \end{split}$$

and

$$\begin{split} &\mathcal{M}\ell_{n} \llbracket (om\ ml)\ sl \rrbracket \\ &= \lambda \rho l_{1} \dots l_{n} \kappa \sigma. \mathcal{M}\ell_{n-1} \llbracket (ml)\ sl \rrbracket \rho l_{2} \dots l_{n} (\mathcal{M}_{out} \llbracket (om \rrbracket) \rho \kappa l_{1} (\sigma_{3}\ l_{1})) \\ &\qquad \qquad (\sigma_{1}, \sigma_{2}, \sigma_{3} \lceil \text{`uninitialized'/l_{1}} \rceil) \\ &= \lambda \rho l_{1} \dots l_{n} \kappa \sigma. P_{n-1\,2} (\mathcal{M}\ell_{n-1} \llbracket (ml)\ sl \rrbracket, \mathcal{M}_{out} \llbracket (om \rrbracket) \rho l_{2} \dots l_{n} \kappa l_{1} (\sigma_{3}\ l_{1}) \\ &\qquad \qquad (\sigma_{1}, \sigma_{2}, \sigma_{3} \lceil \text{`uninitialized'/l_{1}} \rceil) \\ &= pass_{n}\ P_{n-1\,2} (\mathcal{M}\ell_{n-1} \llbracket (ml)\ sl \rrbracket, \mathcal{M}_{out} \llbracket (om \rrbracket)) \end{split}$$

The last transformation to be presented is the equation for computing actual parameters:

$$\begin{array}{l} \mathfrak{A}\ell_{n} \llbracket a \ a \rrbracket = \lambda \rho \eta. \mathfrak{A} \llbracket a \rrbracket \rho (\lambda v. \mathfrak{A}\ell_{n-1} \llbracket a \rrbracket \rho (\eta v)) \\ = D_{0} (\mathfrak{A} \llbracket a \rrbracket, (\lambda \rho \eta v. \mathfrak{A}\ell_{n-1} \llbracket a \rrbracket) \rho (\eta v)) \\ = D_{0} (\mathfrak{A} \llbracket a \rrbracket, T (\mathfrak{A}\ell_{n-1} \llbracket a \rrbracket)) \end{array}$$

Now we may derive the first version of code – a "naive" code represented as a tree in which the internal nodes are labelled with B's, D's, T's, P's and some of the auxiliary functions. The leaves are labelled with actions, i.e. auxiliary functions like lookup[id], fetch, $ext_n id_n \ldots id_1$, and so on. We may omit almost all the indices since they can easily be computed from the information contained in the leaves. We keep indices only with such operations as $block_n$, $function_n$, $pass_n$, $check_n$ and $apply_n$.

The combinator trees are not linear yet. Therefore they are not acceptable for designing a target machine. Figure 1 shows the "naive" code for the program from Example 1; Figure 2 – for the program from Example 2.

4 Code rotation

We can rotate the "naive" code into an almost linear form using the following properties of the combinators:

Property 1. Right-associativity of D's (cf. [4])

$$D_k(D_p(\alpha,\beta),\gamma) = D_{k+p}(\alpha,D_k(\beta,\gamma))$$

Property 2. Elimination of P's

$$P_{n,m}(P_{n,r}(\alpha,\beta),\gamma) = P_{n,m+r}(\alpha,D_m(\beta,\gamma))$$

Proof:

$$P_{n m}(P_{n r}(\alpha, \beta), \gamma)\rho l_1 \dots l_n x_0 x_1 \dots x_m x_{m+1} \dots x_{m+r}$$

$$= P_{n r}(\alpha, \beta)\rho l_1 \dots l_n (\gamma \rho x_0 x_1 \dots x_m) x_{m+1} \dots x_{m+r}$$

$$= \alpha \rho l_1 \dots l_n (\beta \rho (\gamma \rho x_0 x_1 \dots x_m) x_{m+1} \dots x_{m+r})$$

$$= \alpha \rho l_1 \dots l_n (D_m(\beta, \gamma) \rho x_0 x_1 \dots x_m x_{m+1} \dots x_{m+r})$$

$$= P_{n, m+r}(\alpha, D_m(\beta, \gamma))\rho l_1 \dots l_n x_0 x_1 \dots x_m x_{m+1} \dots x_{m+r}$$

Property 3. Sequencing P's and D's

$$P_{n\,m}(D_{n+r}(\alpha,\beta),\gamma) = D_{n+m+r}(\alpha,P_{n\,m}(\beta,\gamma))$$

Proof:

$$P_{n m}(D_{n+r}(\alpha, \beta), \gamma)\rho l_{1} \dots l_{n}x_{0}x_{1} \dots x_{m}x_{m+1} \dots x_{m+r}$$

$$= D_{n+r}(\alpha, \beta)\rho l_{1} \dots l_{n}(\gamma \rho x_{0}x_{1} \dots x_{m})x_{m+1} \dots x_{m+r}$$

$$= \alpha \rho(\beta \rho l_{1} \dots l_{n}(\gamma \rho x_{0}x_{1} \dots x_{m})x_{m+1} \dots x_{m+r})$$

$$= \alpha \rho(P_{n m}(\beta, \gamma)\rho l_{1} \dots l_{n}x_{0}x_{1} \dots x_{m}x_{m+1} \dots x_{m+r})$$

$$= D_{n+m+r}(\alpha, P_{n m}(\beta, \gamma))\rho l_{1} \dots l_{n}x_{0}x_{1} \dots x_{m}x_{m+1} \dots x_{m+r}$$

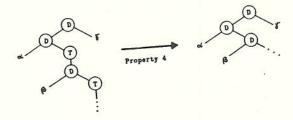


Figure 3. Elimination of T combinators

Property 4. Elimination of T's (due to Wand)

$$D_k(T(\alpha), \beta) = D_{k+1}(\alpha, \beta)$$

Proof:

$$D_k(T(\alpha), \beta)\rho x_0 x_1 \dots x_k x_{k+1}$$

$$= T(\alpha)\rho(\beta\rho x_0 x_1 \dots x_k) x_{k+1}$$

$$= \alpha\rho(\beta\rho x_0 x_1 \dots x_k x_{k+1})$$

$$= D_{k+1}(\alpha, \beta)\rho x_0 x_1 \dots x_k x_{k+1}$$

Notice that Property 4 makes it possible to eliminate all of T's since they occur only in trees of the form shown in Fig. 3.

Property 5. Elimination of return (cf. [3])

$$D_k(return, \gamma) = \gamma$$

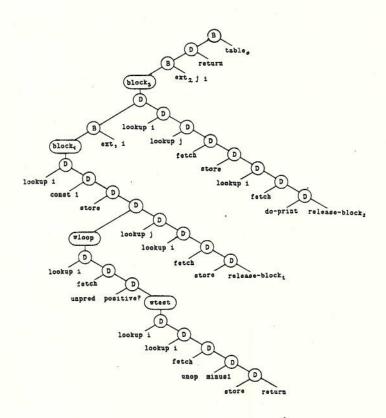


Figure 4. Example 1 - code after rotation

Property 6. Reducing indices at P's

$$P_{nm}(pass_{n+r}, \alpha, \beta) = pass_{n+m+r}P_{n-1,m}(\alpha, \beta)$$

Proof:

```
\begin{array}{l} P_{n\,m}(pass_{n+r}\,\alpha,\beta)\rho l_1\ldots l_nx_0x_1\ldots x_mx_{m+1}\ldots x_{m+r}\sigma\\ = pass_{n+r}(\alpha)\rho l_1\ldots l_n(\beta\rho x_0x_1\ldots x_m)x_{m+1}\ldots x_{m+r}\sigma\\ = \alpha\rho l_2\ldots l_n(\beta\rho x_0x_1\ldots x_m)x_{m+1}\ldots x_{m+r}l_1(\sigma_3\,l_1)\langle\sigma_1,\sigma_2,\sigma_3[\text{ `uninitialized'}/l_1]\rangle\\ = P_{n-1,m}(\alpha,\beta)\rho l_2\ldots l_nx_0x_1\ldots x_mx_{m+1}\ldots x_{m+r}l_1(\sigma_3\,l_1)\langle\sigma_1,\sigma_2,\sigma_3[\text{ `uninitialized'}/l_1]\rangle\\ = pass_{n+m+r}P_{n-1,m}(\alpha,\beta)\rho l_1\ldots l_nx_0x_1\ldots x_mx_{m+1}\ldots x_{m+r}\sigma\end{array}
```

Since the value of n at P_{nm} is equal to the number of pass'es following this P, then after pulling a P through all of D's and pass'es, the P becomes of the form $P_{0m} = D_m$ (by Properties 2, 3 and 6). Therefore it is possible to eliminate all P's from the code.

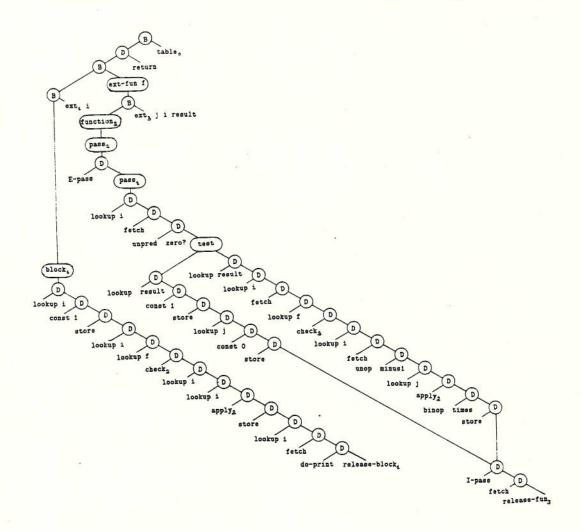


Figure 5. Example 2 - code after rotation

We may also sequence conditional statements with the rest of the code. We need, however, to introduce a new auxiliary function (cf. [6]):

$$test_k fg = \lambda \rho x_0 x_1 \dots x_k \beta.\beta \rightarrow f \rho x_0 x_1 \dots x_k, g \rho x_0 x_1 \dots x_k$$

Notice that we could define $test_k$ by means of test and the T combinator. In that case, however, Ts would remain after rotation. Now we have:

Property 7. Sequencing test's and the rest of the code (cf. [6])

$$D_k(test \ \alpha \beta, \gamma) = test_k (D_k(\alpha, \gamma), D_k(\beta, \gamma))$$

Of course, to avoid duplicating the code for γ , we represent the code after rotation as a dag instead of a tree (we may use the same code for both branches). We do not sequence the code of a while loop. This problem is discussed thoroughly in [6].

```
rot[D[D \alpha \beta] \gamma] = rot[D \alpha [D \beta \gamma]]
                                                                              by Property 1
rot[D [test \alpha \beta] \gamma] = [test rot[D \alpha \gamma] rot[D \beta \gamma]]
                                                                              by Property 7
rot[D \ return \ \beta] = rot \beta
                                                                              by Property 5
rot[D[T\alpha]\beta] = rot[D\alpha\beta]
                                                                              by Property 4
rot[D \alpha \beta] = [D rot\alpha rot\beta]
rot[D[P \alpha \beta] \gamma] = rot[D rot[P \alpha \beta] \gamma]
rot[B \alpha \beta] = [B rot \alpha rot \beta]
rot[wloop \alpha] = [wloop rot \alpha]
rot[wtest \, \alpha] = [wtest \, rot \, \alpha]
rot[block_n \ \alpha] = [block_n \ rot \ \alpha]
rot[ext-fun\ id\ \alpha] = [ext-fun\ id\ rot\alpha]
                                                                              by Property 2
rot[P[P \alpha \beta] \gamma] = rot[P \alpha rot[D \beta \gamma]]
rot[P[D \alpha \beta] \gamma] = rot[D \alpha [P \beta \gamma]]
                                                                              by Property 3
rot[P[pass \alpha] \beta] = [pass rot[P \alpha \beta]]
                                                                              by Property 6
rot\alpha = \alpha
                                                                              for the rest (instructions)
```

Table 8. Structural definition of rot

Now we are able to define the function rot to rotate the "naive" code into an almost linear tree (dag). The definition is shown in Table 8. The rotated trees for Example 1 and Example 2 are of the form from Figures 4 and 5 respectively.

There are two rules that introduce double rotation of the code. This fact causes some problems like rotation of a tree which has been already rotated (corresponding rules are not shown in Table 8). One of these rules may be easily substituted by $rot[P[P\alpha\beta]\gamma] = rot[P\alpha[D\beta\gamma]]$. The new definition is equivalent to the old one since P becomes D at the end of rotation, and then we can rotate the result accordingly to Property 1. There is no such substitution for the rule $rot[D[P\alpha\beta]\gamma] = rot[Drot[P\alpha\beta]\gamma]^*$. Therefore the code must still be rotated twice. It is possible, however, to restrict the double rotation to the code for parameter passing, and eliminate the P combinators before rotating the rest of the code.

5 Static scoping

In the same way as it has been done in [4], we may distribute the symbol table information to instructions. The combinator S is used to sequence instructions after this process:

$$S_{pn}(\alpha,\beta) = \lambda a_1 \dots a_p \kappa x_1 \dots x_n \cdot \alpha a_1 \dots a_p (\beta a_1 \dots a_p \kappa x_1 \dots x_n)$$

The a's correspond to the locations of variables visible in the environment, the x's create a local register file for evaluating expressions.

The symbol table information has been originally distributed by means of the B combinator. Here, however, we need to introduce a generalization of B to obtain the same goal:

$$A_{pij}(\alpha,\beta) = \lambda a_1 \dots a_p b_1 \dots b_i c_1 \dots c_j \cdot \alpha(\beta a_1 \dots a_p b_1 \dots b_i c_1 \dots c_j) c_1 \dots c_j b_1 \dots b_i c_1 \dots c_j$$

All the λ -variables create a new display of locations; therefore they all are passed to the function defining the environment (β) . The j top-most variables (c's) are locations of parameters to be passed. So they are passed as arguments to α , which probably contains

We had not realized this difficulty until we were implementing this method in Scheme

```
test_{pk} f g = \lambda a_1 \dots a_p \kappa x_1 \dots x_k \beta.\beta \rightarrow f a_1 \dots a_p \kappa x_1 \dots x_k, g a_1 \dots a_p \kappa x_1 \dots x_k
wloop_p f = \lambda a_1 \dots a_p \kappa. fix (f a_1 \dots a_p \kappa)
wtest_p f = \lambda a_1 \dots a_p \kappa \theta.\beta.\beta \rightarrow f a_1 \dots a_p \theta. \kappa
block_{pn} f = \lambda a_1 \dots a_p \kappa \sigma. let (l_1, \dots l_n) = new_n \sigma \text{ and } \sigma' = adjoin_n \sigma l_1 \dots l_n
in f a_1 \dots a_p l_1 \dots l_n \kappa \sigma'
function_{pn} f = \lambda a_1 \dots a_p \eta x v_1 \dots v_n \sigma. let (l_0, l_1, \dots l_n) = new_{n+1} \sigma
and \sigma' = adjoin-init_{n+1} \sigma l_0 l_1 \dots l_n \text{ `uninitialized'} v_1 \dots v_n
in f a_1 \dots a_p l_0 l_1 \dots l_n \eta l_0
apply_{pn} = \lambda a_1 \dots a_p \eta f v_1 \dots v_n \cdot f \eta f v_1 \dots v_n
pass_{p+mn m} f = \lambda a_1 \dots a_p l_1 \dots l_m \kappa x_1 \dots x_n \sigma. f a_1 \dots a_p l_1 \dots l_m \kappa x_1 \dots x_n l_1(\sigma_3 l_1)
(\sigma_1, \sigma_2, \sigma_3 [\text{`uninitialized'}/l_1])
release-block_{p+n n} = \lambda a_1 \dots a_p l_1 \dots l_n \eta v \sigma. \eta v (release_n \sigma l_1 \dots l_n)
```

Table 9. Auxiliaries for distributing the symbol table information

some of the pass instructions. The b's and c's together correspond to the newly created locations and they are passed to α as arguments for one of the release instructions. Notice that A_{p00} is equal to B_p .

Now we formulate some useful properties of these combinators:

Property 8. Associativity of B's (cf. [5])

$$B_{\mathfrak{p}}(B_1(\alpha,\beta),\gamma) = B_{\mathfrak{p}}(\alpha,B_{\mathfrak{p}}(\beta,\gamma))$$

Property 9. Distribution law for B (cf. [5])

$$B_p(D_m(\alpha,\beta),\gamma) = S_{pm}(B_p(\alpha,\gamma),B_p(\beta,\gamma))$$

Property 10. Distribution law for A

$$A_{pij}(D_{m+i+2j}(\alpha,\beta),\gamma) = S_{p+i+j,m}(B_{p+i+j}(\alpha,\gamma),A_{pij}(\beta,\gamma))$$

Proof:

$$\begin{array}{l} A_{pij}(D_{m+i+2j}(\alpha,\beta),\gamma)a_1\ldots a_pb_1\ldots b_ic_1\ldots c_jx_0x_1\ldots x_m\\ &=D_{m+i+2j}(\alpha,\beta)(\gamma a_1\ldots a_pb_1\ldots b_ic_1\ldots c_j)c_1\ldots c_jb_1\ldots b_ic_1\ldots c_jx_0x_1\ldots x_m\\ &=\alpha(\gamma a_1\ldots a_pb_1\ldots b_ic_1\ldots c_j)\\ &\qquad (\beta(\gamma a_1\ldots a_pb_1\ldots b_ic_1\ldots c_j)c_1\ldots c_jb_1\ldots b_ic_1\ldots c_jx_0x_1\ldots x_m)\\ &=B_{p+i+j}(\alpha,\gamma)a_1\ldots a_pb_1\ldots b_ic_1\ldots c_j(A_{pij}(\beta,\gamma)a_1\ldots a_pb_1\ldots b_ic_1\ldots c_jx_0x_1\ldots x_m)\\ &=S_{p+i+j,m}(B_{p+i+j}(\alpha,\gamma),A_{pij}(\beta,\gamma))a_1\ldots a_pb_1\ldots b_ic_1\ldots c_jx_0x_1\ldots x_m)\end{array}$$

Before we reformulate the instructions, notice that, by the above properties, the only instructions that are bound to the symbol table information by the A combinator instead of B, are test, release-block, release-fun and pass. And even more, test and release's are bound by means of A_{pi0} (see the reformulation of pass below).

$$\begin{array}{l} A_{p\,i\,0}(test_k\;f\;g,\tau) = test_{p+i,k}\;A_{p\,i\,0}(f,\tau)\;A_{p\,i\,0}(g,\tau)\\ A_{p\,i\,0}(release-block_i,\tau) = release-block_{p+i,i}\\ A_{p\,i\,0}(release-fun_i,\tau) = release-fun_{p+i,i}\\ A_{p\,i\,0}(release-fun_i,\tau) = pass_{p+i+j,n,j}\;A_{p\,i+1\,j-1}(f,\tau)\\ B_p(wloop\;f,\tau) = wloop_p\;B_p(f,\tau)\\ B_p(wloop\;f,\tau) = wloop_p\;B_p(f,\tau)\\ B_p(wtest\;f,\tau) = wtest_pB_p(f,\tau)\\ B_p(block_n\;f,\tau) = block_{p\,n}\;A_{p\,n\,0}(f,\tau)\\ B_p(function'_n\;f,\tau) = function_{p\,n}\;A_{p\,1\,n}(f,\tau)\\ B_p(apply'_n,\tau) = apply_{p\,n} \end{array}$$

Table 10. Distributing the symbol table information

Let us define the environment-creating functions first:

$$table_p \ id \ \tau = \lambda a_1 \dots a_p. (\lambda id'. \ id' = id \rightarrow a_p, \tau a_1 \dots a_{p-i} \ id'$$
$$fun-table_p \ id \ f \ \tau = \lambda a_1 \dots a_p. (\lambda id'. \ id' = id \rightarrow f \ a_1 \dots a_p, \tau a_1 \dots a_p \ id')$$

By means of these functions, we have:

$$B_p(ext_n \ id_n \dots id_1, \tau) = table_{p+n} \ id_n \dots (table_{p+1} \ id_1 \ \tau) \dots$$

$$B_p(ext\text{-}fun \ id \ f, \tau) = fix (\lambda \tau'.fun-table_p \ id \ B_p(f, \tau') \ \tau)$$

We use the definitions of the environment-creating functions to define the value of *lookup* only. And because of the static scoping, we may define other functions that give us the same answer and do not require the environment to be passed during run-time. These are:

$$selec_p j = \lambda a_1 \dots a_p \eta. \eta a_j$$

$$mk \text{-} fun_p j = \lambda a_1 \dots a_p \eta. \eta (f a_1 \dots a_j)$$

Now we may define the value of lookup[id] with the symbol table information τ , given as a term defining τ , in the following way.

Let
$$j = \max\{k \mid \tau = \dots (table_k \ id \dots) \dots \ \text{or} \ \tau = \dots (fun-table_k \ id \ f \dots) \dots\}$$

Then:

- if $\tau = \dots (table_j \ id \dots) \dots$ and $\tau \neq \dots (fun-table_j \ id \dots) \dots$ and, in addition, id describes a regular variable, value or result parameter, then

$$B_p(lookup[id], \tau)a_1...a_p\eta = \eta(\tau a_1...a_p id) = \eta a_j$$

= $selec_p j a_1...a_p\eta$

80

$$B_p(lookup[id], \tau) = selec_p j$$

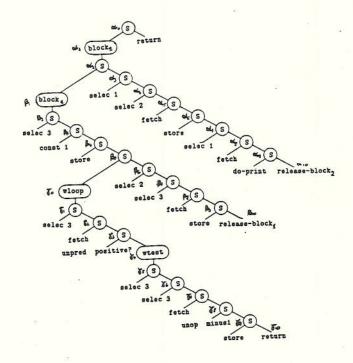


Figure 6. Example 1 - code after distribution

- if τ is defined as in the previous case, but id describes a fun or var parameter, then

$$\begin{split} S_{p\,n}(B_p(lookup[id],\tau),\alpha)a_1\dots a_p\kappa x_1\dots x_n\sigma \\ &= lookup[id](\tau\,a_1\dots a_p)(\alpha a_1\dots a_p\kappa x_1\dots x_n)\sigma \\ &= (\alpha a_1\dots a_p\kappa x_1\dots x_n)(\sigma_3\,a_j)\sigma \\ &= fetch(\tau\,a_1\dots a_p)(\alpha a_1\dots a_p\kappa x_1\dots x_n)a_j\sigma \\ &= S_{p\,n}(fetch_p,\alpha)a_1\dots a_p\kappa x_1\dots x_na_j\sigma \\ &= selec_p\,j\,a_1\dots a_p(S_{p\,n}(fetch_p,\alpha)a_1\dots a_p\kappa x_1\dots x_n)\sigma \\ &= S_{p\,n}(selec_p\,j,S_{p\,n}(fetch_p,\alpha))a_1\dots a_p\kappa x_1\dots x_n\sigma \end{split}$$
 So in this case
$$S_{p\,n}(B_p(lookup[id],\tau),\alpha) = S_{p\,n}(selec_p\,j,S_{p\,n}(fetch_p,\alpha))$$

- if
$$\tau = \dots (fun\text{-}table_j \ id \ f \dots) \dots$$
, i.e. id denotes a regular function, then
$$B_p(lookup[\![id]\!],\tau)a_1\dots a_p\eta = \eta(\tau a_1\dots a_p \ id) = \eta(fa_1\dots a_f) \\ = mk\text{-}fun_{pj} \ f \ a_1\dots a_p\eta$$
 so
$$B_p(lookup[\![id]\!],\tau) = mk\text{-}fun_{pj} \ f$$

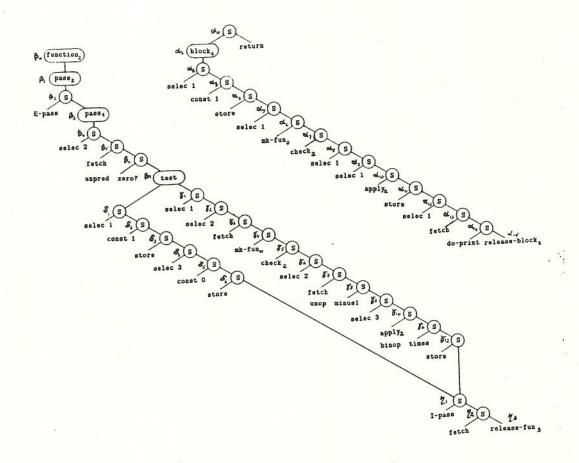


Figure 7. Example 2 - code after distribution

Now we may reformulate the basic instructions such as store, fetch, const, do-print, L-pass etc. The distribution of the symbol table information reaches these instructions as $B_p(\ldots,\tau)$. Since they ignore the information passed by τ , we may redefine all of them in the following way:

$$B_p(store, \tau) = store_p$$
 for all τ 's

The other auxiliaries are also straightforward. Their new definitions are shown in Table 9. By these definitions we obtain the properties of the distribution collected in Table 10. For the purpose of an easier implementation of a target machine (see Section 6), we introduce an additional parameter to a function call. This parameter is ignored by the function; it is, however, removed from the stack for computing an expression. So we redefine the auxiliaries from the previous sections:

function'_n
$$f$$
 env = $\lambda \eta x$.function_n f env η

$$apply'_n = \lambda \rho \eta f v_1 \dots v_n . f \eta f v_1 \dots v_n$$

and then we have the additional properties in Table 10.

Now we can define the function distr to distribute the symbol table information to the instructions, according to the presented rules. The definition is simple and therefore it is omitted. Then the compiler for the language is a function $compile[p] = distr[B rot[D \mathcal{B}\ell[p]] return] table_0]$. Figures 6 and 7 show the codes for Example 1 and 2 after the distribution.

6 Simple display machine

The machine that interpretes the code generated by the compiler consists of:

- the instruction sequence to be interpreted; let us denote the set of all instructions by Ins.
- the display, i.e. the locations of variables in the environment,
- the continuation register; let us denote all continuations by \overline{K} ,
- the local register file for evaluating expressions.

The values stored in the local register file are:

- storable values when they result from evaluating expressions and actual parameters,
- truth values as results of evaluating boolean expressions,
- instruction sequences for implementing loops (another solution is presented in [6]).

So the local register file is built of elements from W = V + B + Ins. It is of the form of W^n .

The instructions and the instruction sequences to be interpreted are of the following functionality:

$$Ins_{pn} = L^p \to \overline{K} \to W^n \to S \to A$$

So $Ins = \bigcup Ins_{pn}$. Then, if Rep_{α} denotes the machine representations of elements from the domain α , and Rep_{pn} denote the representations of Ins_{pn} , we may define the target machine – a function that interpretes instructions (cf. [5]):

$$M_{pn}: Rep_{pn} \to Rep_L^n \to Rep_{\overline{K}} \to Rep_W^n \to S \to A$$

Let us denote by $retpt_{pn}\beta a_1 \dots a_p \kappa x_1 \dots x_n = \beta a_1 \dots a_p \kappa x_1 \dots x_n$, i.e. the continuation to execute β with the given arguments. The interpretation of a program starts as $M_{00}\beta$ init-cont σ_0 , where β is the instruction sequence of the program and σ_0 is the initial state.

Table 11 presents the interpretation of basic instructions. Here we show some of the more complicated. The "-" operation is the abstraction function from representations to "real" values (cf. [5]).

```
M_{pn}[S \text{ store } \alpha]a_1 \dots a_p \kappa x_1 \dots x_n \sigma
        = M_{p\,n-2}\,\alpha a_1\ldots a_p\,\kappa x_1\ldots x_{n-2}\sigma'
                                                                                              \sigma' = \langle \sigma_1, \sigma_2, \sigma_3[x_n/x_{n-1}] \rangle
M_{pn}[S \text{ do-read } \alpha]a_1 \dots a_p \kappa x_1 \dots x_n \sigma
                                                                                              x_{n+1} = first \sigma_1, \ \sigma' = (rest \sigma_1, \sigma_2, \sigma_3)
        = M_{p\,n+1}\,\alpha a_1 \dots a_p \kappa x_1 \dots x_n x_{n+1} \sigma'
M_{pn}[S \text{ do-print } \alpha]a_1 \dots a_p \kappa x_1 \dots x_n \sigma
         = M_{p\,n-1}\,\alpha a_1\ldots a_p\,\kappa x_1\ldots x_{n-1}\sigma'
                                                                                              \sigma' = (\sigma_1, \sigma_2 \mid\mid z_n, \sigma_3)
M_{pn}[S \text{ fetch } \alpha]a_1 \dots a_p \kappa x_1 \dots x_n \sigma = M_{pn} \alpha a_1 \dots a_p \kappa x_1 \dots x_{n-1} (\sigma_3 x_n) \sigma
M_{pn}[S [const i] \alpha]a_1...a_p \kappa x_1...x_n \sigma = M_{pn+1} \alpha a_1...a_p \kappa x_1...x_n i\sigma
M_{pn}[S [selecj] \alpha]a_1...a_p \kappa x_1...x_n \sigma = M_{pn}\alpha a_1...a_p \kappa x_1...x_n a_j \sigma
                                                                                                                                                                             z = \bigoplus x_{n-1}x_n
M_{pn}[S[binop \oplus] \alpha]a_1 \dots a_p \kappa x_1 \dots x_n \sigma = M_{pn-1} \alpha a_1 \dots a_p \kappa x_1 \dots x_{n-2} x \sigma
M_{pn}[S[unop \ominus] \alpha]a_1 \dots a_p \kappa x_1 \dots x_n \sigma = M_{pn} \alpha a_1 \dots a_p \kappa x_1 \dots x_{n-1} x \sigma
                                                                                                                                                                             z = \ominus x_n
                                                                                                                                                                             z = \langle x_{n-1}x_n \rangle
M_{pn}[S | binpred \prec] \alpha]a_1 \dots a_p \kappa x_1 \dots x_n \sigma = M_{pn-1} \alpha a_1 \dots a_p \kappa x_1 \dots x_{n-2} x \sigma
                                                                                                                                                                             z = ?x_n
M_{pn}[S[unpred?] \alpha]a_1...a_p\kappa x_1...x_n\sigma = M_{pn}\alpha a_1...a_p\kappa x_1...x_{n-1}x\sigma
M_{p0} return a_1 \dots a_p (retpt<sub>pn</sub> \alpha a_1 \dots a_p \kappa x_1 \dots x_n)\sigma = M_{pn} \alpha a_1 \dots a_p \kappa x_1 \dots x_n \sigma
Mo o return init-cont \sigma= init-cont \sigma=\sigma_{\mathcal{E}} | "normal termination"
M_{pn}[SL-pass \alpha]a_1...a_p\kappa x_1...x_n\sigma
        = {\sigma_z || "not a variable passed"
                M_{pn-2}\alpha a_1 \dots a_p \kappa x_1 \dots x_{n-2} \sigma'
                                                                                            \sigma' = (\sigma_1, \sigma_2, \sigma_3[x_n/x_{n-1}]
M_{pn}[S \ E-pass \alpha]a_1 \dots a_p \kappa x_1 \dots x_n \sigma
\{\sigma_2 \parallel \text{"not an expression passed"}\}
                                                                                             \sigma' = \begin{cases} \langle \sigma_1, \sigma_2, \sigma_3[x_n/x_{n-1}] \rangle & \text{if } x_n \in E \\ \langle \sigma_1, \sigma_2, \sigma_3[(\sigma_3 \ x_n)/x_{n-1}] \rangle & \text{if } x_n \in L \end{cases}
               \begin{cases} M_{p\,n-2}\alpha a_1 \dots a_p \kappa x_1 \dots x_{n-2}\sigma^t \end{cases}
M_{pn}[SF-pass \alpha]a_1...a_p\kappa x_1...x_n\sigma
        = \begin{cases} \sigma_{2} \parallel \text{"not a function passed"} \\ M_{p\,n-2} \, \alpha a_{1} \dots a_{p} \kappa x_{1} \dots x_{n-2} \sigma' \end{cases}
                                                                                            \begin{array}{l} \text{if } x_n \not\in F \\ \sigma' = \left\langle \sigma_1, \sigma_2, \sigma_3[x_n/x_{n-1}] \right\rangle \end{array}
M_{pn}[S \ I-pass \ \alpha]a_1 \dots a_p \kappa x_1 \dots x_n \sigma
        = {\sigma_2 || "not a variable passed for result"
                                                                                                      if x_n \not\in L
                                                                                                       \sigma' = \langle \sigma_1, \sigma_2, \sigma_3 [(\sigma_3 \ x_{n-1})/x_n] \rangle
                M_{pn-2} \alpha a_1 \dots a_p \kappa x_1 \dots x_{n-2} \sigma'
```

Table 11. Evaluation of instructions

```
\begin{aligned} M_{pn} &[S[block_m \ \alpha]\beta] a_1 \dots a_p \kappa x_1 \dots x_n \sigma \\ &= block_p \ m \check{\alpha} \check{a}_1 \dots \check{a}_p (\beta \check{a}_1 \dots \check{a}_p \check{\kappa} \check{x}_1 \dots \check{x}_n) \sigma \\ &= \check{\alpha} \check{a}_1 \dots \check{a}_p \check{a}_{p+1} \dots \check{a}_{p+m} (\check{\beta} \check{a}_1 \dots \check{a}_p \check{\kappa} \check{x}_1 \dots \check{x}_n) \sigma' \\ &= M_{p+m \ 0} \alpha a_1 \dots a_p a_{p+1} \dots a_{p+m} (retpt_{p \ n} \beta a_1 \dots a_p \kappa x_1 \dots x_n) \sigma' \\ &\text{where: } (a_{p+1}, \dots a_{p+m}) = new_m \sigma, \ \sigma' = adjoin_m \sigma a_{p+1} \dots a_{p+m} \end{aligned}
```

$$\begin{split} M_{pn}[test_{n-1} & \alpha & \beta]a_1 \dots a_p \kappa x_1 \dots x_n \sigma \\ &= test_{pn-1} \check{\alpha} \check{\beta} \check{a}_1 \dots \check{a}_p \check{x}_1 \dots \check{x}_n \sigma \\ &= \left\{ \check{\alpha} \check{a}_1 \dots \check{a}_p \check{\kappa} \check{x}_1 \dots \check{x}_{n-1} \sigma & \text{if } \check{x}_n = t\check{r}ue \\ \check{\beta} \check{a}_1 \dots \check{a}_p \check{\kappa} \check{x}_1 \dots \check{x}_{n-1} \sigma & \text{if } \check{x}_n = f\check{a}\check{l}se \\ &= \left\{ \begin{matrix} M_{pn-1} \alpha a_1 \dots a_p \kappa x_1 \dots x_{n-1} \sigma & \text{if } x_n = true \\ M_{pn-1} \beta a_1 \dots a_p \kappa x_1 \dots x_{n-1} \sigma & \text{if } x_n = f\check{a}\check{l}se \end{matrix} \right. \end{split}$$

$$M_{pn}[S [wloop \alpha] \beta] a_1 \dots a_p \kappa x_1 \dots x_n \sigma$$

$$= M_{p0}[wloop \alpha] a_1 \dots a_p (retpt_{pn} \beta a_1 \dots a_p \kappa x_1 \dots x_n) \sigma$$

$$M_{p0}[wloop \ \alpha]a_1 \dots a_p \kappa \sigma$$

$$= \check{\alpha}\check{a}_1 \dots \check{a}_p \check{\kappa}[wloop \ \alpha]\sigma$$

$$= M_{p1}\alpha a_1 \dots a_p \kappa[wloop \ \alpha]$$

$$\begin{aligned} M_{p\,2}[wtest\ \alpha]a_1\ldots a_p(retpt_{p\,n}\beta a_1\ldots a_p\kappa x_1\ldots x_n)\theta x\sigma \\ &= \begin{cases} M_{p\,0}\,\alpha a_1\ldots a_p(retpt_{p\,0}\theta a_1\ldots a_p(retpt_{p\,n}\beta a_1\ldots a_px_1\ldots x_n))\sigma & \text{if } x=true \\ M_{p\,n}\,\beta a_1\ldots a_p\kappa x_1\ldots x_n\sigma & \text{if } x=false \end{cases}$$

$$M_{p+i,0} \text{ release-block}_i a_1 \dots a_p l_1 \dots l_i (\text{retpt}_{pn} \alpha a_1 \dots a_p \kappa x_1 \dots x_n) \sigma$$

$$= M_{pn} \alpha a_1 \dots a_p \kappa x_1 \dots x_n \sigma'$$
where $\sigma' = \langle \sigma_1, \sigma_2, \sigma_3 | \text{'unused'/l}_1 | \dots | \text{'unused'/l}_i | \rangle$

$$M_{p+i,1} \text{ release-fun}_i a_1 \dots a_p l_1 \dots l_i (\text{retpt}_{mn} \alpha b_1 \dots b_m \kappa x_1 \dots x_n) x_{n+1} \sigma$$

$$= M_{m,n+1} \alpha b_1 \dots b_m \kappa x_1 \dots x_n x_{n+1} \sigma'$$
where $\sigma' = \langle \sigma_1, \sigma_2, \sigma_3 | \text{ 'unused'/l}_1 | \dots | \text{ 'unused'/l}_i | \rangle$

Notice that release-fun is the only instruction that changes all the elements in the display. Notice also that the memory may be arranged as a stack. The release instructions release the top-most elements in the display, that is those elements, which have been created after all other elements in the display. The locations stored in retpt continuations have been also created before the locations being released (see interpretation of block and apply).

$$\begin{array}{l} M_{p+n,m}[\mathit{pass}_n \ \alpha] a_1 \ldots a_p l_1 \ldots l_n \kappa x_1 \ldots x_m \sigma \\ &= \mathit{pass}_{p+n,m,n} \ \check{\alpha} \check{\alpha}_1 \ldots \check{\alpha}_p \check{l}_1 \ldots \check{l}_n \check{\kappa} \check{x}_1 \ldots \check{x}_m \sigma \\ &= \check{\alpha} \check{\alpha}_1 \ldots \check{\alpha}_p \check{l}_1 \ldots \check{l}_n \check{\kappa} \check{x}_1 \ldots \check{x}_m \check{l}_1 (\sigma_3 \ i_1) \sigma' \\ &= M_{p+n,m+2} \ \alpha a_1 \ldots a_p l_1 \ldots l_n \kappa x_1 \ldots x_m l_1 (\sigma_3 \ l_1) \sigma' \\ &\quad \text{where } \sigma' = \langle \sigma_1, \sigma_2, \sigma_3 [\text{`uninitialized'}/l_1] \rangle \end{array}$$

The only decision that still has to be made is the representation of a function value. We will let it be of the following form: $(function_{pn} \alpha, a_1, \dots a_p)$. A function value is created while mk-fun is interpreted. Such a value is stored in the local register file and in local variables for fun parameters. The interpretation is as follows:

$$\begin{array}{ll} M_{p\,n}[S[mk\text{-}fun_j\;\langle function_{j\,m}\;\alpha\rangle]\;\beta]a_1\ldots a_p\kappa x_1\ldots x_n\sigma\\ &=\;mk\text{-}fun_{p\,j}\;\langle function_{j\,m}\;\alpha\rangle\check{a}_1\ldots\check{a}_p(\check{\beta}\check{a}_1\ldots\check{a}_p\check{\kappa}\check{x}_1\ldots\check{x}_n)\sigma\\ &=\;M_{p,n+1}\;\beta a_1\ldots a_p\kappa x_1\ldots x_n\langle function_{j\,m}\;\alpha,a_1,\ldots a_j\rangle\sigma \end{array}$$

$$M_{pn}[S \ check_m \ \alpha]a_1 \dots a_p \kappa x_1 \dots x_{n-1} \{function_j, \beta, b_1, \dots b_j\}\sigma$$

$$= \begin{cases} \sigma_3 \parallel \text{ "wrong number of arguments"} & \text{if } r \neq m \\ M_{pn} \alpha a_1 \dots a_p \kappa x_1 \dots x_{n-1} \{function_j, \beta, b_1, \dots b_j\}\sigma \end{cases}$$

```
\begin{array}{ll} M_{p,n+1+m}[S\;apply_m\;\alpha]a_1\ldots a_p\kappa x_1\ldots x_n(function_{j\;m}\;\beta,b_1,\ldots b_j)v_1\ldots v_m\sigma\\ &=\;apply_{p\;m}\check{a}_1\ldots\check{a}_p(retpt_{p\;n}\;\check{\alpha}\check{a}_1\ldots\check{a}_p\check{\kappa}\check{x}_1\ldots\check{x}_n)(functi\check{o}n_{j\;m}\;\beta,\check{b}_1,\ldots\check{b}_j)\check{v}_1\ldots\check{v}_m\sigma\\ &=\;\langle functi\check{o}n_{j\;m}\;\beta,\check{b}_1,\ldots\check{b}_j\rangle\langle retpt_{p\;n}\;\check{\alpha}\check{a}_1\ldots\check{a}_p\check{\kappa}\check{x}_1\ldots\check{x}_n\rangle\langle functi\check{o}n\ldots\rangle\check{v}_1\ldots\check{v}_m\sigma\\ &=\;M_{j,m+1}\langle function_{j\;m}\;\beta\rangle b_1\ldots b_j\langle retpt_{p\;n}\;\alpha a_1\ldots a_p\kappa x_1\ldots x_n\rangle\langle function\ldots\rangle v_1\ldots v_m\sigma \end{array}
```

$$\begin{split} M_{p,n+1} &\langle function_{p\,m} \ \alpha \rangle a_1 \dots a_p \kappa \langle function \dots \rangle v_1 \dots v_n \sigma \\ &= \alpha \check{a}_1 \dots \check{a}_p \check{a}_{p+1} \dots \check{a}_{p+n+1} \check{\kappa} \check{a}_{p+1} \sigma' \\ &= M_{p+n+1,1} \ \alpha a_1 \dots a_p a_{p+1} \dots a_{p+n+1} \kappa a_{p+1} \sigma' \\ &\text{where } (a_{p+1}, \dots a_{p+n+1}) = new_{n+1} \sigma \\ &\text{and } \sigma' = adjoin\text{-}init_{n+1} \sigma a_{p+1} \dots a_{p+n+1} \text{'uninitialized'} v_1 \dots v_n \end{split}$$

Appendix A shows the interpretation of the code for Example 1, Appendix B for Example 2.

7 Standard display machine

We would like to obtain the standard display machine, discussed by Dijkstra in [1], as a result of our transformations. In the standard machine, locations of variables from a block or a function form a sequence of consecutive memory cells. The memory is ordered and there exists a function, succ, that for a given location returns the following one. Then a location of a variable can be expressed as a pair: the base, which is the location of the memory block, and the offset, the number of succ's to be performed on the base in order to get the location corresponding to the variable. The display vector is shorter than that presented in the previous sections; it consists only of the bases of all visible blocks.

To be able to get the standard machine by transforming semantic equations for the language, we must already change the equations and introduce the block structure of the memory. It seems strange at first that this "representation" decision must be made when the language is being designed. It is, however, quite natural for languages with class objects, coroutines (Simula 67, Loglan), or pointers to dynamically created records (Pascal). Such languages introduce the notion of objects in their semantics already. Fortunately, this change does not require redefining the entire semantics of our language. The necessary changes are shown in Table 12. Notice the difference in indices of $\mathcal{M}\ell$ from Section 2 and $\mathcal{C}\ell$ here. The index of $\mathcal{M}\ell$ previously indicated the number of parameters still to be passed. The index of $\mathcal{C}\ell$ denotes the (consecutive) number of the parameter being passed, so it indicates the offset of this parameter in the memory block created for the function.

Table 13 shows the new combinatorial forms of the changed semantic equations. We need to replace P combinators by new ones; let us call them NP and define as:

$$NP_n(\alpha, \beta) = \lambda \rho l \kappa x_1 \dots x_n . \alpha \rho l(\beta \rho l \kappa x_1 \dots x_n)$$

They have the following properties:

Continuations

```
variable declaration continuations
Venvc = Env \rightarrow L \rightarrow K
Fenve = Env \rightarrow K
                                 function declaration continuations
```

Meaning functions

```
D_v : (Var-dec) \rightarrow Env \rightarrow Venvc \rightarrow K
D: (Fun-dec) - Env - Fenve - K
Cl_n : (Mode-list-body) \rightarrow Env \rightarrow L \rightarrow K
```

Equations

```
\mathcal{B}\ell[\![(\text{block }(\text{var }id_1\ldots id_n)\text{ sl})\!]] = \lambda\rho\kappa.\mathcal{D}_v[\![(\text{var }id_1\ldots id_n)]\!]\rho(\lambda\rho'l.\mathcal{S}\ell[\![sl]\!]\rho'(\text{release-block}_n\rho'l\kappa))
B\ell[\![(\text{block (fun }\alpha) \ sl)]\!] = \lambda \rho \kappa. D_f[\![(\text{fun }\alpha)]\!] \rho(\lambda \rho'. S\ell[\![sl]\!] \rho' \kappa)
D_v[[(var\ id_1...id_n)]] = \lambda \rho \chi \sigma. let l = new_n \sigma \ and \sigma' = adjoin_n \sigma l
        and \rho' = \rho[l/id_1][(succl)/id_2]...[(succ^{n-1}l)/id_{n-1}]
        in x plo
D_f[\![(\operatorname{fun}\ id\ (id_1\ldots id_n)\ (ml)\ sl)]\!] = \lambda \rho \chi.\chi(\operatorname{fiz}\ (\lambda \rho'.\rho[(f\ \rho')/id]))
        where f is:
        f = \lambda \rho' \eta x v_1 \dots v_n \sigma. Let l = ne w_{n+1} \sigma and \rho'' = \rho' [l/result] [(succl)/id_1] \dots [(succ^n l)/id_n]
                and \sigma' = adjoin-init_{n+1}\sigma l 'uninitialized' v_1 \dots v_n
                in Cl, [(ml) sl] p'l(fetch p" (release-funn+1 p"ln)l)o'
C\ell_n[(empty) sl] = body S\ell[sl]
C\ell_n [(im\ ml)\ sl] = \lambda \rho l \kappa \sigma. let l' = succ^n l
        in M_{in}[im]\rho(\mathcal{C}l_{n+1}[(ml) sl_{n}^{q}\rho l\kappa)l'(\sigma_{s} l')(\sigma_{1},\sigma_{2},\sigma_{s}['uninitialized'/l'])
C\ell_n \llbracket (om\ ml)\ s \rrbracket = \lambda \rho l \kappa \sigma. let\ l' = succ^n\ l
        in Cln+1 [(ml) sl pl (Mout [om] pkl' (os l'))(o1, o2, os ['uninitialized'/l'])
```

Auxiliaries

```
body f = \lambda \rho l. f \rho
new_n\sigma = \text{some } l \text{ such that } (\sigma_{\mathcal{S}} l), (\sigma_{\mathcal{S}}(\text{succl})), \dots (\sigma_{\mathcal{S}}(\text{succ}^{n-1} l)) \text{ are 'unused'}
adjoin_n \ \sigma l = (\sigma_1, \sigma_2, \sigma_3 [`uninitialized'/l] [`uninitialized'/(succl)] \dots [`uninitialized'/(succ^{n-1} l)])
adjoin-init_n \ \sigma lv_1 \dots v_n = \{\sigma_1, \sigma_2, \sigma_3[v_1/l] \dots [v_n/(succ^{n-1} l)]\}
release-block_n = \lambda \, \rho l \kappa \sigma. \kappa (\sigma_1, \sigma_2, \sigma_3 [\text{`unused'/l}]... [\text{`unused'/(succ}^{n-1} \, l)])
release-fun_n = \lambda \rho l\eta v\sigma. \eta v \langle \sigma_1, \sigma_2, \sigma_3 [`unused'/l]...[`unused'/(succ^{n-1}l)] \rangle
```

Table 12. Standard display - modified semantics

Property 11.

- $NP_n(NP_r(\alpha, \beta), \gamma) = NP_{n+r}(\alpha, NP_n(\beta, \gamma))$
- $NP_n(D_r(\alpha,\beta),\gamma) = D_{n+r}(\alpha,NP_n(\beta,\gamma))$ (2)
- $NP_n(pass_{0m} \alpha, \beta) = pass_{nm} NP_n(\alpha, \beta)$ $NP_n(body \alpha, \beta) = D_{n+1}(\alpha, \beta)$

In the previous sections we have standardized the equations to take the environment as a parameter even when it has not been necessary. We could do almost the same now and add the base of the current block to all semantic functions. Then we would not need D combinators at all. We do not, however, demand this standardization; notice that after rotating, NP combinators do not occur in combinator trees (by Property 11(4)).

To distribute the symbol table information to instructions, we need still another modification of B combinators. The new combinators are simpler than A's and may be defined as:

$$NA_p(\alpha, \beta) = \lambda a_1 \dots a_p \cdot \alpha(\beta a_1 \dots a_p) a_p$$

```
Auxiliaries
                     = \lambda \rho l \kappa x_1 \dots x_m \sigma. let l' = succ^n l
pass<sub>mn</sub> f
                            in f \rho l \kappa x_1 \dots x_m l'(\sigma_3 l')(\sigma_1, \sigma_2, \sigma_3 ['uninitialized'/l'])
                     = \lambda \kappa \sigma. let l = new_n \sigma and \sigma' = adjoin_n \sigma l
blockn fenv
                            in f(envl)lko
ext_n \ id_n \dots id_1 = \lambda \rho l. \rho [l/id_1] \dots [(succ^{n-1} l)/id_n]
function, f env= \lambda \eta x v_1 \dots v_n \sigma. let l = new_{n+1} \sigma and \sigma' = adjoin-init_{n+1} \sigma l 'uninitialized' v_1 \dots v_n
                            in f(envl)lylo
                                                                Equations
B\ell[(block\ (var\ id_1...id_n)\ sl)] = B_1(block_nD_1(\S\ell[sl], release-block_n), ext_n\ id_n...id_1)
B\ell[\![(block (fun id (id_1...id_n) (ml) sl_1) sl_2)]\!] = B_1(S\ell[\![sl_2]\!], ezt-funidf)
where f is:
       f = B_1(function_n NP_1(Cl_1[(ml) sl_1], D_1(fetch, release-fun_{n+1})), ext_{n+1} id_n ... id_1 result)
C\ell_n[(empty) sl] = body S\ell[sl]
C\ell_n \llbracket (imml) \ sl \rrbracket = pass_0 \ n D_1 (M_{in} \llbracket im \rrbracket, C\ell_{n+1} \llbracket (ml) \ sl \rrbracket)
C\ell_n[(om\ ml)\ sl] = pass_{0n} NP_n(C\ell_{n+1}[(ml)\ sl], Mout[om])
                         Table 13. Standard display - combinatorial equations
                                                               Auxiliaries
                 table p id i \tau = \lambda a_1 \dots a_p id' . id' = id \rightarrow succ^i a_p, \tau a_1 \dots a_p id'
                 new-frame, \tau = \lambda a_1 \dots a_p id' \cdot \tau a_1 \dots a_{p-1} id'
                 B_p(ext_n id_n...id_1, \tau) = table_p id_n n - 1...(table_p id_1 0 (new-frame_p \tau))...
                 selec_p(j,i) = \lambda a_1 \dots a_p.succ^i a_j
                 pass_{pmn} f = \lambda a_1 \dots a_p \kappa x_1 \dots x_m \sigma.
                               let l = succ^n a_p, Comband \sigma' = (\sigma_1, \sigma_2, \sigma_3['uninitialized'/l])
                               in fa_1 \dots a_p \kappa x_1 \dots x_m l(\sigma_s l) \sigma'
                 block_{pn} f = \lambda a_1 \dots a_p \kappa \sigma. let l = new_n \sigma \text{ and } \sigma' = adjoin_n \sigma l
                               in fa1...aplko
                 function<sub>pn</sub> f = \lambda a_1 \dots a_p \eta x v_1 \dots v_n \sigma
                               let l = ne w_{n+1} \sigma and \sigma' = adjoin-init_{n+1} \sigma l 'uninitialized' v_1 \dots v_n
                               in fa1...aplylo
                 releasen \sigma = \lambda l. \{\sigma_1, \sigma_2, \sigma_3 [\text{`unused'/l}]...[\text{`unused'/(suce}^{n-1}l)]\}
                 release-block_{pn} = \lambda a_1 \dots a_p \kappa \sigma . \kappa (release_n \sigma a_p)
                 release-fun_{pn} = \lambda a_1 \dots a_p \eta v \sigma. \eta v (release_n \sigma a_p)
                                                              Distribution
                 let \tau = \dots (table_j \ id \ i\dots) \dots or \tau = \dots (fun-table_j \ id \ f\dots) \dots
                       if id denotes a variable without dereferencing
                                  S_{pn}(B_p(lookup[id], \tau), \beta) = S_{pn}(selec_p(j, i), \beta)
                       if id denotes a var or fun parameter
                                   S_{pn}(B_p(lookup[id], \tau), \beta) = S_{pn}(selec_p(j, i), S_{pn}(fetch, \beta))
                       if id denotes a regular function
                                  S_{pn}(lookup[id], \tau), \beta) = S_{pn}(mk-fun_{pj} f, \beta)
                 NA_p(test_k f g, \tau) = test_{pk} NA_p(f, \tau) NA_p(g, \tau)
                 NA_p(release-block_i, \tau) = release-block_pi
                 NA_p(release-fun_{pi}, \tau) = release-fun_{pi}
                 NA_p(pass_{mn} f, \tau) = pass_{pmn} NA_p(f, \tau)
                 B_p(block_n f, \tau) = block_p n NA_p(f, \tau)
                 B_p(function_n f, \tau) = function_{p,n} NA_p(f, \tau)
```

Table 14. Standard display - distribution

that is NA copies the last parameter which is the base of the current block. NA combinators have the following property:

Property 12.

$$NA_p(D_{m+1}(\alpha, \beta), \gamma) = S_{pm}(B_p(\alpha, \beta), NA_p(\beta, \gamma))$$

The new environment-creating functions and the values of the auxiliaries applied to NA are shown in Table 14. The pair (i,j) in the new version of selec means the base (i) and the offset (j) of the variable. The transformations are simpler for the standard display, and, as we have already said, they would be even simpler if our equations were in the new standardized form. We think that the machine architecture as well as the interpreting function of M are trivial to define. Therefore we will not define them here.

8 Final remarks

Further modifications may be done in order to obtain a target-machine code that resembles a conventional assembly-language program. One of these modifications has been presented by Wand in [6]. He has introduced a binding operator label that makes it possible to implement loops in the standard way, i.e. not storing continuations in the stack (or local register file). This operator is statically scoped and it is a subject for rotation, that is it has the following property ([6]):

$$rot(D_k(while-loop(x, y), z)) = label\theta. rot(D_k(x, test_k(D_k(y, \theta), z)))$$

We can prove that we still are able to distribute the symbol table information to this code, and by introducing pointers, we can eliminate the variable θ entirely ([6]).

After this modification, our code is not linear; it is also not a dag. To be able to store the code in a linear memory, we should introduce "jumps". They may be of the form similar to retpt, that is:

$$cont_k \theta = \lambda \rho \kappa x_1 \dots x_k \cdot \theta \rho \kappa x_1 \dots x_k$$

Notice that because the label operator is closed and the value produced by evaluating the loop condition is absorbed by test, the first occurrence of θ is of the same functionality as that bound by cont. So the number of parameters passed to θ remains the same. The cont combinator may be useful for conditionals as well.

Another modification, also suggested by Wand, is introduction of "complex" combinators that eliminate S. We may define them in the following way:

$$STORE_{pn} \beta = S_{pn}(store_n, \beta)$$

These combinators together with cont produce a code of a "linear" form. The exceptions are test and block. A "linear" representation of $test_n \ \alpha \beta$ is easy; one may store this instruction as $(TEST_{pn} \ \alpha) \beta$, where α is a pointer of the same form as this used by cont. Of course, the cont combinator may be also used at the end of the β sequence.

To linearize blocks we may introduce a combinator of the following form:

$$back_{pn} \alpha \beta = \lambda a_1 \dots a_p \kappa x_1 \dots x_n \cdot \alpha a_1 \dots a_p (\beta a_1 \dots a_{p-1} \kappa x_1 \dots x_n)$$

and then show that

$$back_{pn} S_{pm}(\alpha, \beta) \gamma = S_{pn+m}(\alpha, back_{pn} \beta \gamma)$$

Since for the solutions presented so far the local register file is empty when a release-block instruction is being evaluated, we may also have:

RELEASE-BLOCK_{pni}
$$\alpha = \lambda a_1 \dots a_p \kappa x_1 \dots x_n \sigma.\alpha a_1 \dots a_{p-1} \kappa x_1 \dots x_n \langle \sigma_1, \sigma_2, \sigma_3 ['unused'/a_p] \dots ['unused'/(succ^{i-1} a_p)] \rangle$$

and then:

$$back_{pn}$$
 (release-block_{pi} α) = RELEASE-BLOCK_{pni} α

By these properties we may define:

$$BLOCK_{pni} \alpha = \lambda a_1 \dots a_p \kappa x_1 \dots x_n \sigma \cdot \alpha a_1 \dots a_p a_{p+1} \kappa x_1 \dots x_n \sigma'$$

where $a_{p+1} = new_i \sigma$ and $\sigma' = adjoin_i \sigma a_{p+1}$ and

$$S_{pn}(block_{pi} \alpha, \beta) = BLOCK_{pni}(back_{p+1n} \alpha \beta)$$

In this way we eventually obtain a linear code of the desired form. Notice that we do not need the retpt combinator to enter a block anymore.

Still another question concerns when checking of parameters passed to a function takes place. It is, however, connected with the language design, not the method discussed here. If the formal function had its parameters specified, then it could be possible to carry out all the checking of L-pass, E-pass and I-pass during compilation. F-pass, however, would contain a complex checker of function specifications or the formal functions would have to be restricted in some way. That is:

- the current solution specifies (fun f (i g) (var fun)...) and applications of g need a run-time checking of the number of parameters as well as the kind of parameters passed,
- when specifying g in the same way as f, i.e. (fun f (i g) (var fun(var fun (value)))...) we avoid the need of any run-time checking; in this case, however, it is impossible to specify a function that may be applied to itself (infinite chain of fun specifications),
- specification of g does not define the second-level function's parameters (as in Loglan), i.e. (fun f(ig) (var fun(var fun))...) where the fun parameter of g does not contain any specification of its parameters; then the run-time checking is needed for F-pass only.

These solutions would result in different codes generated by the compiler. For languages which are not strongly-typed (Simula 67, Loglan) L-pass, E-pass, I-pass and F-pass may serve as the type checker for applications, and in the general case must be carried out when the program is being executed.

References

- [1] Dijkstra, E.W. "Recursive Programming", Numerische Mathematik 2,1960 also in Programming Systems and Languages, S.Rosen (Ed.), McGraw-Hill, New York, 1967
- [2] Gordon, M.J.C. "The Denotational Description of Programming Languages", Springer-Verlag, New York, 1979
- [3] Li-Mei Wu, C-616 Project, Indiana University, 1982 (manuscript)
- [4] Wand, M. "Semantics-Directed Machine Architecture", Conf. Rec. 9th ACM Symp. on Principles of Programming Languages (1982), 234-241
- [5] Wand, M. "Deriving Target Code as a Representation of Continuation Semantics" ACM Trans. on Prog. Lang. and Systems, 4, 3, July, 1982, 496-517
- [6] Wand, M. "Loops in Combinator-Based Compilers" Conf. Rec. 10th ACM Symp. on Principles of Prog. Lang. (1983), 190-196

Appendix A. Interpretation of Example 1

Let σ_0 be the initial state. Since we are not to read and the **print** statement occurs only at the and of the program, we show the changes of the third component of the state only. The locations are bold-typed integers. The labels used are the labels from Figure 6. We also label continuations.

```
M_{00}(\alpha_0: S[block_2 \alpha_2] return])init-cont \sigma_0
    \rightarrow M_{20}(\alpha_2: [S[block_1 \beta_2] \alpha_3]) \mathbf{12} \kappa_1 : (retpt_{00} return init-cont) \sigma_1
                         where \sigma_1: \mathbf{1} \rightarrow \text{`uninitialized'}, \mathbf{2} \rightarrow \text{`uninitialized'}
             M_{30}(\beta_2: [S [selec 3] \beta_3]) \mathbf{123} \kappa_2: retpt_{20} \alpha_3 \mathbf{12} \kappa_1) \sigma_2
                         where \sigma_2: \mathbf{1} \rightarrow \text{`uninitialized'}, \mathbf{2} \rightarrow \text{`uninitialized'}, \mathbf{3} \rightarrow \text{`uninitialized'}
             M_{31}(\beta_3: [S [cons 1] \beta_4]) 123\kappa_2 3\sigma_2
    \rightarrow M_{32}(\beta_4: [S store \beta_5]) \mathbf{123} \kappa_2 \mathbf{31} \sigma_2
             M_{30}(\beta_5: [S[wloop \gamma_2] \beta_6]) 123 \kappa_2 \sigma_3
                         where \sigma_3; 1 \rightarrow 'uninitialized', 2 \rightarrow 'uninitialized', 3 \rightarrow 1
    \rightarrow M_{30}(\gamma_1: [wloop \gamma_2]) 123\kappa_3: (retpt_{30} \beta_6 123\kappa_2)\sigma_3
    \rightarrow M_{31}(\gamma_2: [S[selec 3] \gamma_3]) \mathbf{123} \kappa_3 \gamma_1 \sigma_3
    \rightarrow M_{32}(\gamma_3: [S fetch \gamma_4]) \mathbf{123} \kappa_3 \gamma_1 \mathbf{3} \sigma_3
    \rightarrow M_{32}(\gamma_4: [S[unpred positive?] \gamma_5]))123\kappa_3\gamma_11\sigma_3
    \rightarrow M_{32}(\gamma_5: [wtest \gamma_6]) 123 \kappa_3 \gamma_1 true \sigma_3
    \rightarrow M_{30}(\gamma_6: [S | selec 3 | \gamma_7]) \mathbf{123} \kappa_4: (retpt_{30} \gamma_1 \mathbf{123} \kappa_3) \sigma_3
    \rightarrow M_{31}(\gamma_7: [S[selec 3] \gamma_8]) \mathbf{123} \kappa_4 \mathbf{3} \sigma_3
    \rightarrow M_{32}(\gamma_8: [S fetch \gamma_9]) 123\kappa_4 33\sigma_3
    \rightarrow M_{32}(\gamma_9: [S [unop minus1] \gamma_{10}]) 123 \kappa_4 31 \sigma_3
    \rightarrow M_{32}(\gamma_{10}: [S store \gamma_{11}]) 123\kappa_4 30\sigma_3
    \rightarrow M_{30}(\gamma_{11}: return) 123\kappa_4: (retpt_{30} \gamma_1 123\kappa_3)\sigma_4
                         where \sigma_4: \mathbf{1} \to \text{`uninitialized'}, \mathbf{2} \to \text{`uninitialized'}, \mathbf{3} \to 0
    \rightarrow M_{30}(\gamma_1: [wloop \gamma_2]) 123\kappa_3\sigma_4
    \rightarrow M_{31}(\gamma_2: [S [selec 3] \gamma_3]) \mathbf{123} \kappa_3 \gamma_1 \sigma_4
    \rightarrow M_{32}(\gamma_3: [S fetch \gamma_4]) \mathbf{123} \kappa_3 \gamma_1 \mathbf{3} \sigma_4
    \rightarrow M_{32}(\gamma_4: [S[unpred positive?] \gamma_5]) 123 \kappa_3 \gamma_1 0 \sigma_4
    \rightarrow M_{32}(\gamma_5: [wtest \gamma_6])123\kappa_3: (retpt_{30} \beta_6 123\kappa_2)\gamma_1 false \sigma_4
    \rightarrow M_{30}(\beta_6: [S[selec 2] \beta_7]) 123\kappa_2\sigma_4
    \rightarrow M_{31}(\beta_7: [S[selec 3] \beta_8]) \mathbf{123} \kappa_2 \sigma_4
    \rightarrow M_{32}(\beta_8: [S fetch \beta_9]) 123\kappa_2 2\sigma_4
    \rightarrow M_{32}(\beta_9: [S store \beta_{10}]) 123 \kappa_2 20 \sigma_4
             M_{30}(\beta_{10}: release-block_1) 123\kappa_2: (retpt_{20} \ \alpha_3 \ 12\kappa_1)\sigma_5
                          where \sigma_{\delta}: \mathbf{1} \to \text{`uninitialized'}, \mathbf{2} \to 0, \mathbf{3} \to 0
             M_{20}(\alpha_3:[S[selec\ 1]\ \alpha_4])\mathbf{12}\kappa_1\sigma_6
                          where \sigma_6: \mathbf{1} \rightarrow \text{`uninitialized'}, \mathbf{2} \rightarrow 0, \mathbf{3} \rightarrow \text{`unused'}
          M_{21}(\alpha_4: [S[selec 2] \alpha_5]) \mathbf{12} \kappa_1 \mathbf{10}
    \rightarrow M_{22}(\alpha_{\delta}: [S fetch \alpha_{\delta}]) 12\kappa_{1} 12\sigma_{\delta}
    → M22(α6: |S store α7|)12κ1 10σ6
             M_{20}(\alpha_7: [S | selec 1] | \alpha_8]) \mathbf{12} \kappa_1 \sigma_7
                          where \sigma_7: \mathbf{1} \to 0, \mathbf{2} \to 0
    \rightarrow M_{21}(\alpha_8: [S fetch \alpha_9]) 12\kappa_1 1\sigma_7
            M_{21}(\alpha_9:[S \text{ do-print }\alpha_{10}])\mathbf{12}\kappa_1\mathbf{0}\sigma_7
             M_{20}(\alpha_{10}: release-block_2) 12\kappa_1: (retpt_{00} return init-cont)\sigma_7
                          do-print prints 0 into the second component of the state
           Moo(return) init-cont o8
                          where \sigma_8: \mathbf{1} \rightarrow \text{'unused'}, \mathbf{2} \rightarrow \text{'unused'}
```

 \rightarrow init-cont σ_8 produces the answer: 0 "normal termination"

Appendix B. Interpretation of Example 2

This example shows how functions and function calls are interpreted. As in Appendix A, we show only the changes of the third component of σ . Since we have to distinguish the values from different components of V, we denote locations as bold-typed integers – it may be implemented by using tag bits for values in V. The labels for instruction sequences come from Figure 7; σ_0 is the initial state.

```
M_{00}(\alpha_0: [S[block_1 \ \alpha_2] \ return]) \ init-cont\sigma_0
     \rightarrow M_{10}(\alpha_2: [S[selec 1] \alpha_3]) \mathbf{1} \kappa_1: (retpt_{00} return init-cont) \sigma_1
                          where \sigma_1: \mathbf{1} \rightarrow \text{`uninitialized'}
    \rightarrow M_{11}(\alpha_3: [S [const 1] \alpha_4]) \mathbf{1} \kappa_1 \mathbf{1} \sigma_1
    \rightarrow M_{12}(\alpha_4: [S store \alpha_5]) \mathbf{1} \kappa_1 \mathbf{1} \mathbf{1} \sigma_1
             M_{10}(\alpha_5: [S[selec 1] \alpha_6]) \mathbf{1} \kappa_1 \sigma_2
                          where \sigma_2: \mathbf{1} \to 1
             M_{11}(\alpha_8: [S[mk-fun_0, \beta_0], \alpha_7]) \mathbf{1}\kappa_1 \mathbf{1}\sigma_2
    \rightarrow M_{12}(\alpha_7: [S \ check_2 \ \alpha_8]) \mathbf{1} \kappa_1 \mathbf{1} f: (function_{02} \ \beta_1) \sigma_2
    \rightarrow M_{12}(\alpha_8: [S[selec 1] \alpha_9]) \mathbf{1} \kappa_1 \mathbf{1} f \sigma_2
    \rightarrow M_{13}(\alpha_9: [S[selec 1] \alpha_{10}]) \mathbf{1} \kappa_1 \mathbf{1} f \mathbf{1} \sigma_2
    \rightarrow M_{14}(\alpha_{10}: [S apply_2 \alpha_{11}]) \mathbf{1} \kappa_1 \mathbf{1} f \mathbf{1} \mathbf{1} \sigma_2
    \rightarrow M_{03}(\beta_0: function_{02} \beta_1)\kappa_2: (retpt_{11} \alpha_{11} \mathbf{1}\kappa_1 \mathbf{1})f \mathbf{1}\mathbf{1}\sigma_2
             M_{31}(\beta_1: [pass_2 \ \beta_2]) 234\kappa_2 2\sigma_3
                          where \sigma_3: \mathbf{1} \to \mathbf{1}, \mathbf{2} \to \text{`uninitialized'}, \mathbf{3} \to \mathbf{1}, \mathbf{4} \to \mathbf{1}
             M_{33}(\beta_2: [S E-pass \beta_3]) 234\kappa_2 231\sigma_4
                          where \sigma_4: \mathbf{1} \to \mathbf{1}, \mathbf{2} \to \text{`uninitialized'}, \mathbf{3} \to \text{`uninitialized'}, \mathbf{4} \to \mathbf{1}
             M_{31}(\beta_3: [pass_1 \ \beta_4]) 234 \kappa_2 2\sigma_5
                          where \sigma_{\delta}: \mathbf{1} \to 1, \mathbf{2} \to \text{`uninitialized'}, \mathbf{3} \to 1, \mathbf{4} \to \mathbf{1}
             M_{33}(\beta_4: [S[selec 2] \beta_5])234\kappa_2241\sigma_6
                          where \sigma_6: \mathbf{1} \to 1, \mathbf{2} \to \text{`uninitialized'}, \mathbf{3} \to 1, \mathbf{4} \to \text{`uninitialized'}
             M_{34}(\beta_5: [S fetch \beta_6]) 234\kappa_2 2413\sigma_6
    \rightarrow M_{34}(\beta_6: [S[unpred zero?] \beta_7]) 234\kappa_2 2411\sigma_6
    \rightarrow M_{34}(\beta_7: [test \delta_1 \gamma_1]) 234 \kappa_2 241 false \sigma_8
    \rightarrow M_{33}(\gamma_1: [S[selec 1] \gamma_2]) 234 \kappa_2 241 \sigma_6
    \rightarrow M_{34}(\gamma_2: [S [selec 2] \gamma_3]) 234 \kappa_2 2412 \sigma_6
    \rightarrow M_{35}(\gamma_3: [S fetch \sigma_4]) 234\kappa_2 24123\sigma_6
    \rightarrow M_{35}(\gamma_4: [S[mk-fun_0 \beta_0] \gamma_5]) 234\kappa_2 24121\sigma_6
    \rightarrow M_{38}(\gamma_5: [S \ check_2 \ \gamma_8]) 234\kappa_2 24121f: (function_{02} \ \beta_1)\sigma_8
    \rightarrow M_{36}(\gamma_6: [S[selec 2] \gamma_7]) 234 \kappa_2 24121 f \sigma_6
    \rightarrow M_{37}(\gamma_7: [S fetch \gamma_8]) 234\kappa_2 24121 f 3\sigma_6
    \rightarrow M_{37}(\gamma_8: [S[unop\ minus1]\ \gamma_9]) 234\kappa_2 24121f 1\sigma_6
    \rightarrow M_{37}(\gamma_9: [S[selec 3] \gamma_{10}]) 234 \kappa_2 24121 \int 0 \sigma_6
    \rightarrow M_{38}(\gamma_{10}: [S \ apply_2 \ \gamma_{11}]) 234\kappa_2 24121f0 4\sigma_6
    \rightarrow M_{03}(\beta_0: function_{02}\beta_1)\kappa_3: (retpt_{35}\gamma_{11} 234\kappa_2 24121) f 004\sigma_6
    \rightarrow M_{31}(\beta_1: [pass_2 \beta_2]) 567 \kappa_3 5\sigma_7
                          where \sigma_7: \mathbf{1} \to 1, \mathbf{2} \to \text{'uninitialized'}, \mathbf{3} \to 1, \mathbf{4}, \mathbf{5} \to \text{'uninitialized'},
                                                 6 \rightarrow 0, 7 \rightarrow 4
             M_{33}(\beta_2: [S E-pass \beta_3]) 567 \kappa_3 560 \sigma_8
                          where \sigma_8: \mathbf{1} \to \mathbf{1}, \mathbf{2} \to \text{'uninitialized'}, \mathbf{3} \to \mathbf{1}, \mathbf{4}, \mathbf{5}, \mathbf{6} \to \text{'uninitialized'},
                                                 7 \rightarrow 4
             M_{31}(\beta_3: [pass_1 \ \beta_4]) 567 \kappa_3 5\sigma_9
                          where \sigma_0: 1 \to 1, 2 \to \text{`uninitialized'}, 3 \to 1, 4, 5 \to \text{`uninitialized'},
                                                 3 \rightarrow 0.7 \rightarrow 4
```

```
M_{33}(\beta_4): [S[selec 2] \beta_5]) 567 \kappa_3 574 \sigma_{10}
                     where \sigma_{10}: 1 \to 1, 2 \to \text{`uninitialized'}, 3 \to 1, 4, 5 \to \text{`uninitialized'},
                                            6 - 0, 7 - 'uninitialized'
         M_{34}(\beta_{\delta}: [S fetch \beta_{\delta}]) 567\kappa_{3} 5746\sigma_{10}
         M_{34}(\beta_6: [S | unpred zero?] \beta_7]) 567 \kappa_3 5740 \sigma_{10}
\rightarrow M_{34}(\beta_7: [test \delta_1 \gamma_1]) 567\kappa_3 574 true \sigma_{10}
\rightarrow M_{33}(\delta_1: [S[selec 1] \delta_2]) 567 \kappa_3 574 \sigma_{10}
\rightarrow M_{34}(\delta_2: [S [const 1] \delta_3]) 567 \kappa_3 5745 \sigma_{10}
\rightarrow M_{35}(\delta_3: [S store \delta_4]) 567 \kappa_3 57451 \sigma_{10}
         M_{33}(\delta_4: |S| selec 3 | \delta_5 |) 567 \kappa_3 574 \sigma_{11}
                     where \sigma_{11}: \mathbf{1} \to \mathbf{1}, \mathbf{2} \to \text{'uninitialized'}, \mathbf{3} \to \mathbf{1}, \mathbf{4} \to \text{'uninitialized'},
                                            5 \rightarrow 1, 6 \rightarrow 0, 7 \rightarrow 'uninitialized'
         M_{34}(\delta_5: [S [const 0] \delta_6]) 567 \kappa_3 5747 \sigma_{11}
\rightarrow M_{35}(\delta_6: [S store \eta_1) 567 \kappa_3 57470 \sigma_{11}
         M_{33}(\eta_1: [S I-pass \eta_2]) 567\kappa_3 574\sigma_{12}
                     where \sigma_{12}: \mathbf{1} \to \mathbf{1}, \mathbf{2} \to \text{'uninitialized'}, \mathbf{3} \to \mathbf{1}, \mathbf{4} \to \text{'uninitialized'}, \mathbf{5} \to \mathbf{1},
                                            6 \rightarrow 0, 7 \rightarrow 0
         M_{31}(\eta_2: [S fetch \eta_3]) 567\kappa_3 5\sigma_{13}
                     where \sigma_{13}: 1 \to 1, 2 \to \text{`uninitialized'}, 3 \to 1, 4 \to 0, 5 \to 1, 6 \to 0,
                                            7 \rightarrow 0
         M_{31}(\eta_3): release-fun<sub>3</sub>) 567\kappa_3: (retpt<sub>35</sub> \gamma_{11} 234\kappa_2 24121) 1\sigma_{13}
         M_{36}(\gamma_{11}; [S[binop\ times]\ \gamma_{12}]) 234\kappa_2 241211\sigma_{14}
                     where \sigma_{14}: \mathbf{1} \to \mathbf{1}, \mathbf{2} \to \text{'uninitialized'}, \mathbf{3} \to \mathbf{1}, \mathbf{4} \to \mathbf{0}, \mathbf{5}, \mathbf{6}, \mathbf{7} \to \text{'unused'}
         M_{35}(\gamma_{12}: [S \ store \ \eta_1]) 234\kappa_2 24121\sigma_{14}
         M_{33}(\eta_1: [S I-pass \eta_2]) 234\kappa_2 241\sigma_{15}
                     where \sigma_{15}: \mathbf{1} \to \mathbf{1}, \mathbf{2} \to \mathbf{1}, \mathbf{3} \to \mathbf{1}, \mathbf{4} \to \mathbf{0}
         M_{31}(\eta_2: [S fetch \eta_3]) 234 \kappa_2 2\sigma_{16}
                     where \sigma_{16}: \mathbf{1} \to 0, \mathbf{2} \to 1, \mathbf{3} \to 1, \mathbf{4} \to 0
         M_{31}(\eta_3: release-fun_3)234\kappa_2: (retpt_{11} \alpha_{11} \mathbf{1} \kappa_1 \mathbf{1}) \mathbf{1} \sigma_{16}
         M_{12}(\alpha_{11}: [S \ store \ \alpha_{12}]) \mathbf{1} \kappa_1 \mathbf{1} \mathbf{1} \sigma_{17}
                     where \sigma_{17}: \mathbf{1} \rightarrow 0, \mathbf{2}, \mathbf{3}, \mathbf{4} \rightarrow 'unused'
         M_{10}(\alpha_{12}: [S[selec 1] \alpha_{13}]) \mathbf{1} \kappa_1 \sigma_{18}
                     where \sigma_{18}: \mathbf{1} \to 1
\rightarrow M_{11}(\alpha_{13}: [S fetch \alpha_{14}]) \mathbf{1} \kappa_1 \mathbf{1} \sigma_{18}
\rightarrow M_{11}(\alpha_{14}: [S print \alpha_{15}]) \mathbf{1} \kappa_1 \mathbf{1} \sigma_1 \mathbf{8}
        M_{10}(\alpha_{15}: release-block_1)\mathbf{1}\kappa_1: (retpt_{00} return init-cont)\sigma_{19}
                     The second component of \sigma_{19} contains 1
\rightarrow M_{00} (return) init-cont\sigma_{20}
                                                                        \sigma_{20}: \mathbf{1} \rightarrow `unused'
        init-cont o20
                                                   produces the answer: 1 "normal termination"
```

Notice that the value of the function call is transmitted after all result parameters (states σ_{17} and σ_{18} for instance).