

An Overview to
Polyhedral Model



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Polyhedral Model

- ▶ A framework for performing loop transformation
- ▶ Loop representation: using polytopes to achieve fine-grain representation of program
- ▶ Loop transformation: transforming loop by doing affine transformation on polytopes
- ▶ Dependency test: several mathematical methods for validating transformation on loop polytopes
- ▶ Code generation: generate transformed code from loop polytopes



Benefits?

- ▶ Fine-grained representation of program
- ▶ Dependency Graph:
 - ▶ Each node corresponds with one statement in source program
 - ▶ Syntax based



Benefits?

- ▶ Fine-grained representation of program
- ▶ **Dependency Graph:**
 - ▶ Each node corresponds with one statement in source program
 - ▶ Syntax based
- ▶ **Polyhedral Model:**
 - ▶ Each point in polytope corresponds with one instance of statement
 - ▶ Finer grained analysis and transformation is possible



Program Abstraction Level

- ▶ **Statement**

```
For (I=1; I<=10; I++)
```

```
    A[I] = A[I-1] + 1
```

- ▶ **Operation (Instance of statement)**

```
A[4] = A[3] + 1
```



Iteration Domain

▶ Iteration Vector

- ▶ A n-level loop nest can be represented as a n-entry vector, each component corresponding to each level loop iterator

```
For (x1=L1;x1<U1;x1++)  
  ...  
  For (x2=L2;x2<U2;x2++)  
    ...  
    ...  
    For (xn=Ln;xn<Un;xn++)  
      ...
```

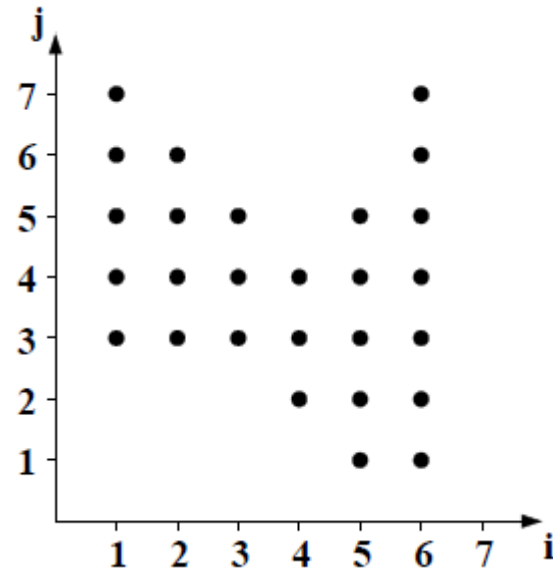
$$\vec{x} = \begin{pmatrix} x1 \\ x2 \\ \cdot \\ \cdot \\ \cdot \\ xn \end{pmatrix}$$



Iteration Domain

- ▶ Iteration Domain: Set of all possible iteration vectors for a given statement

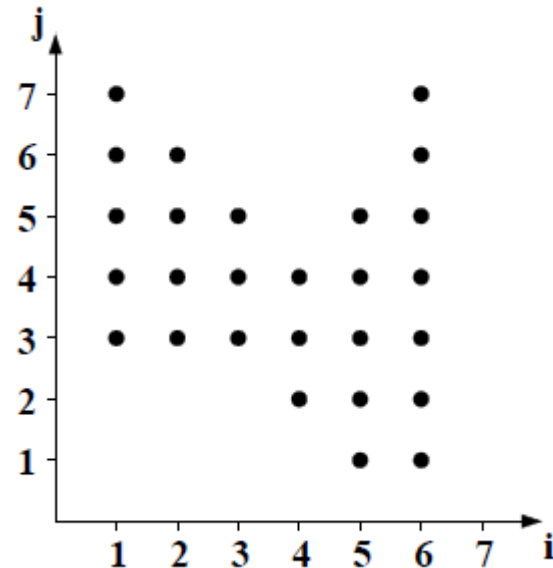
```
For (i=1;i<=6;i++)  
  For (j=min(max(6-1,1),3);  
      j<=max(8-i,2*i-5);  
      j++)  
    a[i][j]=a[i-1][j];
```



Iteration Domain

- ▶ Iteration Domain: Set of all possible iteration vectors for a given statement

```
For (i=1;i<=6;i++)  
  For (j=min(max(6-1,1),3);  
      j<=max(8-i,2*i-5);  
      j++)  
    a[i][j]=a[i-1][j];
```



Notice: This iteration domain is not valid for polyhedral model!



Iteration Domain

- ▶ Iteration domain can be a polytope since it is the set of n -dimension vectors
- ▶ For polyhedral model, the iteration domain must be a convex set.



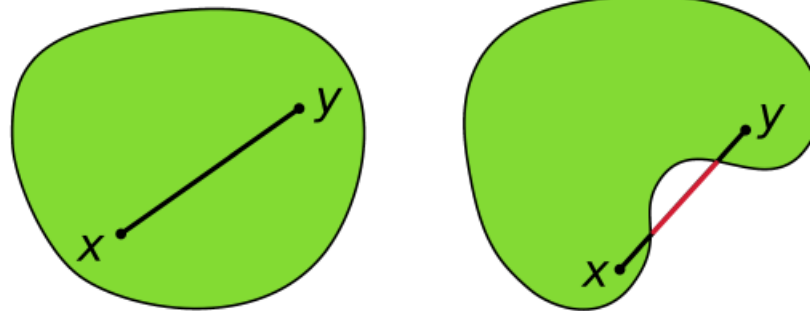
Iteration Domain

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- ▶ Convex Set:
 - ▶ In simple words: For a line segment between any two point in set S , each point on this segment should be in S .



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Iteration Domain

- ▶ Iteration domain can be a polytope since it is the set of n-dimension vectors
- ▶ For polyhedral model, the iteration domain must be a convex set.
- ▶ Convex Set:
 - ▶ In simple words: For a line segment between any two point in set S, each point on this segment should be in S.
- ▶ \mathbb{Z} -Polyhedron
 - ▶ In most situation loop counters are integers
 - ▶ So we use a polyhedron of integer points to represent loop iteration domain



Modeling Iteration Domains

- ▶ Dimension of Iteration Domain: Decided by loop nesting levels
- ▶ Bounds of Iteration Domain: Decided by loop bounds
 - ▶ Using inequalities

```
For (i=1;i<=n;i++)  
  For (j=1;j<=n;j++)  
    if (i<=n+2-j)  
      b[j]=b[j]+a[i];
```

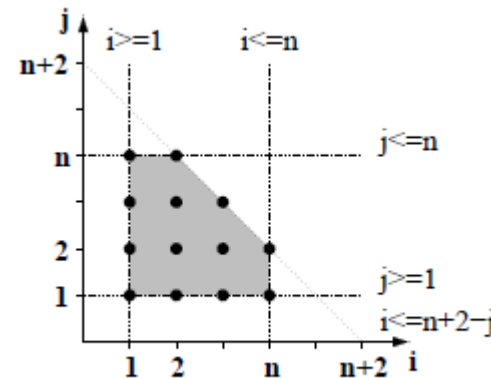


Modeling Iteration Domains

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For (i=1;i<=n;i++)  
  For (j=1;j<=n;j++)  
    if (i<=n+2-j)  
      b[j]=b[j]+a[i];
```

$$1 \leq i \leq n, 1 \leq j \leq n$$
$$i \leq n + 2 - j$$



Modeling Iteration Domains

- ▶ Representing iteration bounds by affine function:

$$1 \leq i \leq n : \begin{bmatrix} 1 & 0 \\ -1 & 0 \end{bmatrix} \begin{pmatrix} i \\ j \end{pmatrix} + \begin{pmatrix} -1 \\ n \end{pmatrix} \geq 0$$

$$1 \leq j \leq n : \begin{bmatrix} 0 & 1 \\ 0 & -1 \end{bmatrix} \begin{pmatrix} i \\ j \end{pmatrix} + \begin{pmatrix} -1 \\ n \end{pmatrix} \geq 0$$

$$i \leq n + 2 - j : [-1 \quad -1] \begin{pmatrix} i \\ j \end{pmatrix} + (n + 2) \geq 0$$

$$\begin{bmatrix} 1 & 0 \\ -1 & 0 \\ 0 & 1 \\ 0 & -1 \\ -1 & -1 \end{bmatrix} \begin{pmatrix} i \\ j \end{pmatrix} + \begin{pmatrix} -1 \\ n \\ -1 \\ n \\ n + 2 \end{pmatrix} \geq \vec{0}$$



Examples: Iteration Domain

```
For (i=0; i<=N; i++)  
  For (j=0; j<=i; j++)  
    if (i>=M) a[j]=0;
```

$$\begin{bmatrix} 1 & 0 \\ -1 & 0 \\ 0 & 1 \\ 1 & -1 \\ 1 & 0 \end{bmatrix} \begin{pmatrix} i \\ j \end{pmatrix} + \begin{bmatrix} 0 \\ N \\ 0 \\ 0 \\ -M \end{bmatrix} \geq \vec{0}$$



Examples: Iteration Domain

```
For (i=0; i<=N; i+=2)
  For (j=0; j<=N; j++)
    if (i%3==1 && j%2==0) A[i]=0
```

- Can this loop be represented in polyhedral model?
- The if statement can cause “cavities” in polyhedral.



Examples: Iteration Domain

```
For (i=0; i<=N; i+=2)
  For (j=0; j<=N; j++)
    if (i%3==1 && j%2==0) A[i]=0
```

- Can this loop be represented in polyhedral model?
- The if statement can cause “cavities” in polyhedral.
- Use loop normalization



Loop Normalization

▶ **Algorithm:**

1. Replace loop boundaries and steps:

$\text{DO } I=L,U,S \rightarrow \text{DO } i=1,(U-L+S)/S,1$

2. Replace each reference to original loop variable I with:

$i*S-S+L$

3. Reset the loop variable value to ensure the after loop reference to loop variable can get correct value:

$I = i*S-S+L$



Example

```
For (i=0;i<=N;i+=2)
  For (j=0;j<=N;j++)
    if (i%3==1 && j%2==0) A[i]=0
```



Example

```
For (i=0; i<=N; i+=2)
  For (j=0; j<=N; j++)
    if (i%3==1 && j%2==0) A[i]=0
```

```
For (i=4; i<=N; i+=6)
  For (j=0; j<=N; j+=2)
    A[i]=0
```



Example

```
For (i=0;i<=N;i+=2)
  For (j=0;j<=N;j++)
    if (i%3==1 && j%2==0) A[i]=0
```

```
For (i=4;i<=N;i+=6)
  For (j=0;j<=N;j+=2)
    A[i]=0
```

```
For (ii=1;ii<=(N+2)/6;ii++)
  For (jj=1;jj<=(N+2)/2;jj++)
    i=ii*6-6+4
    j=jj*2-2
    A[i]=0
```



Example

```
For (ii=1;ii<=(N+2)/6;ii++)
  For (jj=1;jj<=(N+2)/2;jj++)
    i=ii*6-6+4
    j=jj*2-2
    A[i]=0
```

$$\begin{bmatrix} 1 & 0 \\ -1 & 0 \\ 0 & 1 \\ 0 & -1 \end{bmatrix} \begin{pmatrix} i \\ j \end{pmatrix} + \begin{bmatrix} 1 \\ (N+2)/6 \\ 1 \\ (N+2)/2 \end{bmatrix} \geq \vec{0}$$



Review: Dependency

- ▶ There exists a data dependency from statement s_1 to s_2 if and only if:
 - ▶ s_1 and s_2 access to same memory location and at least one of them stores into it
 - ▶ A feasible execution path exists from s_1 to s_2
- ▶ These rules can be extended to polyhedral model.



Review: Dependency

- ▶ There exists a data dependency from statement s_1 to s_2 if and only if:
 - ▶ s_1 and s_2 access to same memory location and at least one of them stores into it
 - ▶ A feasible execution path exists from s_1 to s_2
- ▶ These rules can be extended to polyhedral model.
- ▶ Dependency Polyhedral:
 - ▶ Array reference function: indicating reference to same memory
 - ▶ Iteration domain
 - ▶ Precedence order: indicating execution path



Dependency Polyhedral

- ▶ **Array reference function:**

- ▶ For statement s and r accessing same array:

- ▶ $F_s \vec{x}_s + \vec{a}_s = F_r \vec{x}_r + \vec{a}_r$



Dependency Polyhedral

- ▶ **Array reference function:**

- ▶ For statement s and r accessing same array:

- ▶ $F_s \vec{x}_s + \vec{a}_s = F_r \vec{x}_r + \vec{a}_r$

- ▶ **Precedence order function:**

- ▶ Statement s is textually before statement r :

- ▶ $P_s \vec{x}_s - P_r \vec{x}_r + \vec{b} \geq \vec{0}$



Construction Dependency Polyhedral

- ▶ The dependence polyhedron for $R\delta S$ at a given level i and for a given pair of references to statement r and s is described as Cartesian product of:

$$\overline{\begin{bmatrix} F_s & -F_r \\ D_s & 0 \\ 0 & D_r \\ P_s & -P_r \end{bmatrix}} \left(\begin{array}{c} \overrightarrow{x_s} \\ \overrightarrow{x_r} \end{array} \right) + \overline{\begin{pmatrix} a_s - a_r \\ c_s \\ c_r \\ b \end{pmatrix}} \begin{array}{l} = \overline{0} \\ \geq \overrightarrow{0} \end{array}$$



Examples for Dependency Polyhedron

```
For (i=0;i<=N;i++)  
  For (j=0;j<=N;j++)  
    A[i][j]=A[i+1][j+1]
```



Examples for Dependency Polyhedron

```
For (i=0; i<=N; i++)  
  For (j=0; j<=N; j++)  
    A[i][j]=A[i+1][j+1]    (S1)
```

Iteration Domain:

$$\mathcal{DS}_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \end{bmatrix} \begin{pmatrix} i \\ j \\ n \\ 1 \end{pmatrix} \geq \vec{0}$$



Examples for Dependency Polyhedron

```
For (i=0; i<=N; i++)  
  For (j=0; j<=N; j++)  
    A[i][j]=A[i+1][j+1]    (S1)
```

Array Reference Function:

$$F_A(\vec{x}_{s1}) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \begin{pmatrix} i \\ j \\ n \\ 1 \end{pmatrix}$$

$$F_{A'}(\vec{x}_{s1}) = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix} \begin{pmatrix} i \\ j \\ n \\ 1 \end{pmatrix}$$



Examples for Dependency Polyhedron

```
For (i=0; i<=N; i++)  
  For (j=0; j<=N; j++)  
    A[i][j]=A[i+1][j+1]    (S1)
```

Precedence Order:

For statement S1 in two consecutive loop, $i-i'=1$, $j-j'=1$

$$P_{S1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \begin{pmatrix} i \\ j \\ n \\ 1 \end{pmatrix}$$

To satisfy $P_S \vec{x}_S - P_r \vec{x}_r + \vec{b} \geq \vec{0}$, \vec{b} should be $[-1 \quad -1]$.



Examples for Dependency Polyhedron

```

For (i=0; i<=N; i++)
  For (j=0; j<=N; j++)
    A[i][j]=A[i+1][j+1]    (S1)
  
```

$$\begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \begin{pmatrix} i \\ j \\ i' \\ j' \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ 0 \\ n \\ 0 \\ n \\ 0 \\ n \\ 0 \\ n \\ -1 \\ -1 \end{pmatrix} \stackrel{=}{\geq} \vec{0}$$



Examples for Dependency Polyhedron

```

For (i=0; i<=N; i++)
  For (j=0; j<=N; j++)
    A[i][j]=A[i+1][j+1]    (S1)
  
```

F: Array Reference
Function

$$\begin{bmatrix}
 1 & 0 & 1 & 0 \\
 0 & 1 & 0 & 1 \\
 1 & 0 & 0 & 0 \\
 -1 & 0 & 0 & 0 \\
 0 & 1 & 0 & 0 \\
 0 & -1 & 0 & 0 \\
 0 & 0 & 1 & 0 \\
 0 & 0 & -1 & 0 \\
 0 & 0 & 0 & 1 \\
 0 & 0 & 0 & -1 \\
 1 & 0 & 1 & 0 \\
 0 & 1 & 0 & 1
 \end{bmatrix}
 \begin{pmatrix}
 i \\
 j \\
 i' \\
 j'
 \end{pmatrix}
 +
 \begin{pmatrix}
 1 \\
 1 \\
 0 \\
 n \\
 0 \\
 n \\
 0 \\
 n \\
 0 \\
 n \\
 -1 \\
 -1
 \end{pmatrix}
 \succeq \vec{0}$$



Examples for Dependency Polyhedron

```
For (i=0; i<=N; i++)  
  For (j=0; j<=N; j++)  
    A[i][j]=A[i+1][j+1]    (S1)
```

A: Iteration Domain

$$\begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \begin{pmatrix} i \\ j \\ i' \\ j' \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ 0 \\ n \\ 0 \\ n \\ 0 \\ n \\ 0 \\ n \\ -1 \\ -1 \end{pmatrix} \geq \vec{0}$$



Examples for Dependency Polyhedron

```

For (i=0; i<=N; i++)
  For (j=0; j<=N; j++)
    A[i][j]=A[i+1][j+1]    (S1)
  
```

$$\begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \begin{pmatrix} i \\ j \\ i' \\ j' \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ 0 \\ n \\ 0 \\ n \\ 0 \\ n \\ 0 \\ n \\ -1 \\ -1 \end{pmatrix} \succeq \vec{0}$$

P: Precedence
Order



Examples for Dependency Polyhedron

- ▶ Matrix format using in polyhedral compiling library:

$$\text{Given } \mathcal{D}_{R,S} : \begin{bmatrix} 1 & -1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 \end{bmatrix} \cdot \begin{pmatrix} i_R \\ i_S \\ j_S \\ n \\ 1 \end{pmatrix} \begin{matrix} = 0 \\ \leq 0 \\ \geq 0 \end{matrix}$$

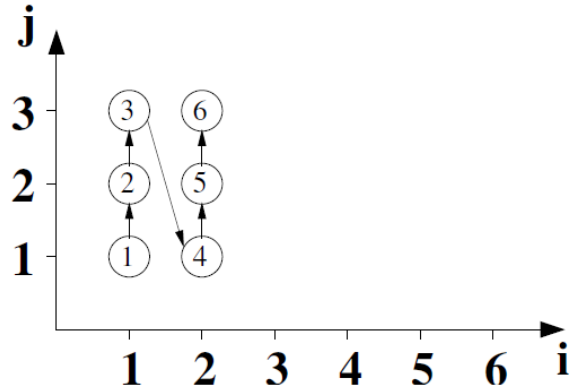
$$\text{It is written: } \begin{bmatrix} 0 & 1 & -1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & -1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & -1 & 1 & 0 \end{bmatrix} \cdot \begin{pmatrix} i_R \\ i_S \\ j_S \\ n \\ 1 \end{pmatrix}$$

On the first column, 0 stands for = 0, 1 for ≥ 0



Transformation using Polytopes: Loop Interchange

Before: For (i=1; i<=2; i++)
 For (j=1; j<=3; j++)

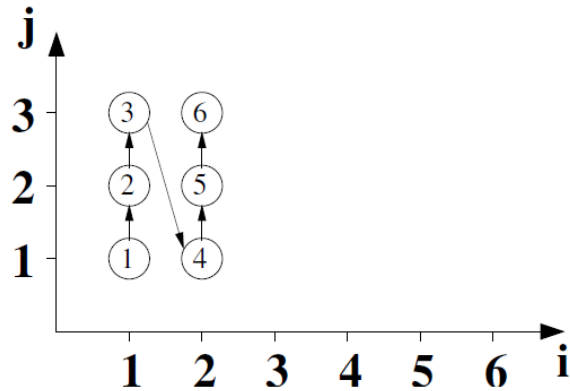


$$\begin{bmatrix} 1 & 0 \\ -1 & 0 \\ 0 & 1 \\ 0 & -1 \end{bmatrix} \begin{pmatrix} i \\ j \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \\ -1 \\ 3 \end{pmatrix} \geq \vec{0}$$



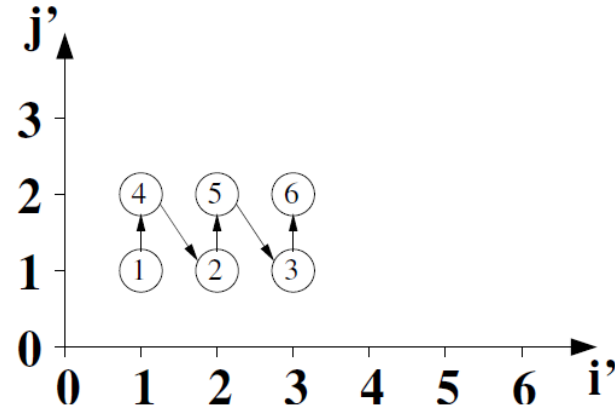
Transformation using Polytopes: Loop Interchange

Before: For (i=1; i<=2; i++)
For (j=1; j<=3; j++)



$$\begin{bmatrix} 1 & 0 \\ -1 & 0 \\ 0 & 1 \\ 0 & -1 \end{bmatrix} \begin{pmatrix} i \\ j \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \\ -1 \\ 3 \end{pmatrix} \geq \vec{0}$$

After: For (j=1; j<=3; j++)
For (i=1; i<=2; i++)



$$\begin{bmatrix} 0 & 1 \\ 0 & -1 \\ 1 & 0 \\ -1 & 0 \end{bmatrix} \begin{pmatrix} i' \\ j' \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \\ -1 \\ 3 \end{pmatrix} \geq \vec{0}$$

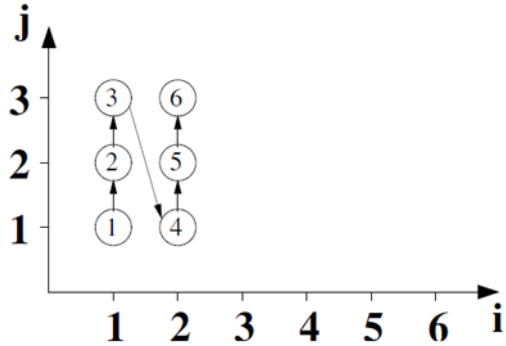
► Transformation Function

$$\begin{pmatrix} i' \\ j' \end{pmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{pmatrix} i \\ j \end{pmatrix}$$



Transformation using Polytopes: Loop Reversal

Before: For (i=1; i<=2; i++)
For (j=1; j<=3; j++)

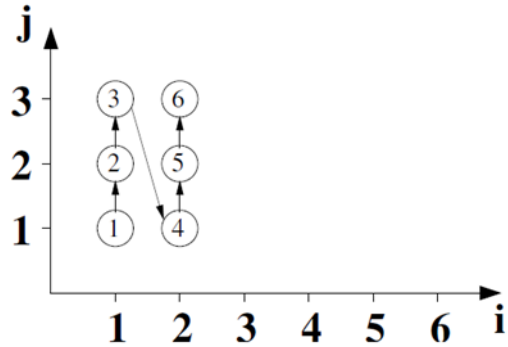


$$\begin{bmatrix} 1 & 0 \\ -1 & 0 \\ 0 & 1 \\ 0 & -1 \end{bmatrix} \begin{pmatrix} i \\ j \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \\ -1 \\ 3 \end{pmatrix} \geq \vec{0}$$



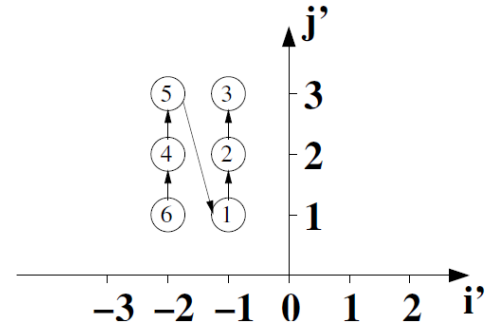
Transformation using Polytopes: Loop Reversal

Before: For ($i=1; i \leq 2; i++$)
For ($j=1; j \leq 3; j++$)



$$\begin{bmatrix} 1 & 0 \\ -1 & 0 \\ 0 & 1 \\ 0 & -1 \end{bmatrix} \begin{pmatrix} i \\ j \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \\ -1 \\ 3 \end{pmatrix} \geq \vec{0}$$

After: For ($i=-1; i \geq -2; i--$)
For ($j=1; j \leq 3; j++$)



$$\begin{bmatrix} -1 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & -1 \end{bmatrix} \begin{pmatrix} i' \\ j' \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \\ -1 \\ 3 \end{pmatrix} \geq \vec{0}$$

► Transformation Function:

$$\begin{pmatrix} i' \\ j' \end{pmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{pmatrix} i \\ j \end{pmatrix}$$

Polyhedral Model: Pros and Cons

- ▶ **Pros:**

- ▶ Finer grained representation, analysis, optimization
- ▶ Especially appropriate for loop transformation



Example of Loop Tiling

- ▶ (From the C-to-CUDA paper, this tiling intends to improve locality)

```
for (i=0;i<N;i++) {
  P: x[i]=0;
  for (j=0;j<N;j++)
    Q: x[i]+=a[j][i]*y[j];
}
```

(a) Original code

$$D_Q^{orig} \cdot \begin{pmatrix} i \\ j \\ N \\ 1 \end{pmatrix} \geq 0 \quad D_Q^{tiled} \cdot \begin{pmatrix} it \\ jt \\ i \\ j \\ N \\ 1 \end{pmatrix} \geq 0$$

(c) Original and tiled iteration space

```
for (it=0;it<=floord(N-1,32);it++) {
  for (jt=0;jt<=floord(N-1,32);jt++) {
    if (jt == 0) {
      for (i=max(32*it,0);
           i<=min(32*it+31,N-1); i++) {
        P: x[i]=0;
        Q: x[i]=x[i]+a[0][i]*y[0];
      }
    }
    for (i=max(32*it,0);
         i<=min(32*it+31,N-1); i++) {
      for (j=max(32*jt,1);
           j<=min(32*jt+31,N-1);j++) {
        Q: x[i]=x[i]+a[j][i]*y[j];
      }
    }
  }
}
```

(b) Tiled code

Polyhedral Model: Pros and Cons

▶ Cons:

- ▶ Efficiency: Compile-time efficiency, since integer programming is NP-complete
- ▶ Building polyhedrons in compile time is also memory consuming



References

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- ▶ C. Bastoul. *Code generation in the polyhedral model is easier than you think*. In PACT'13 IEEE International Conference on Parallel Architecture and Compilation Techniques, pages 7-16, Sept. 2004.
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Thanks!

