Robot Gait Experiments -- General Instructions

Set up There are four components that need to be connected:
1. The robot is connected to its power supply
2(a). The computer connects to its power supply
2(b). The computer is also connected to the robot’s power supply
3. The robot power supply plugs into a wall socket
4. The computer power supply plugs into a wall socket

The computer

to start the computer
The white switch on the left-hand side of the computer turns it on.
It comes up under Windows 95; just CANCEL the password query.

to run the GAIT designer
There are two icons on the desktop: "4-step GAIT" and "6-step GAIT".
Double-click to activate

to shut down the computer
There is a "task bar" at the bottom of the screen.
Click the "START" button, then "Shut Down" to turn off the computer
Windows will display a message when it’s safe to turn off the power (white switch)